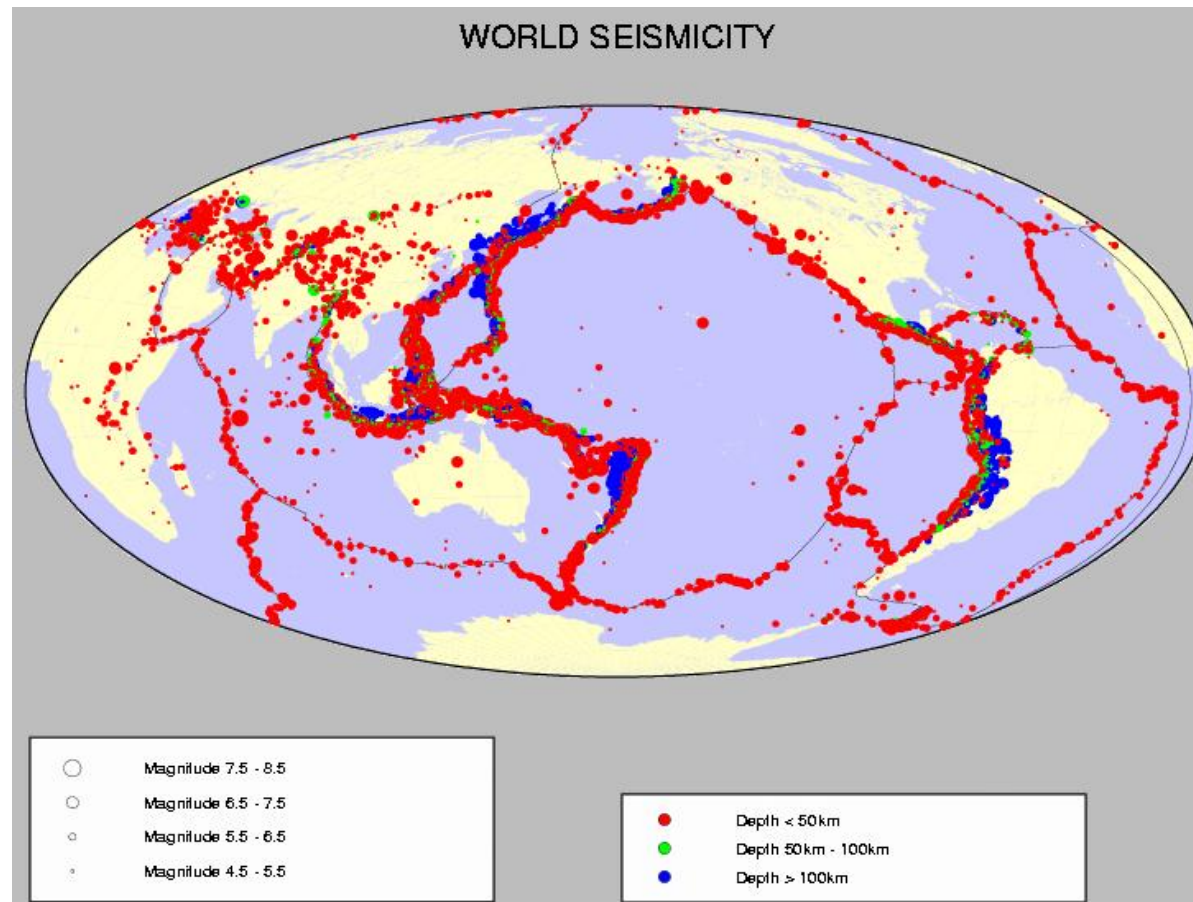


RIGID PLATE TECTONICS

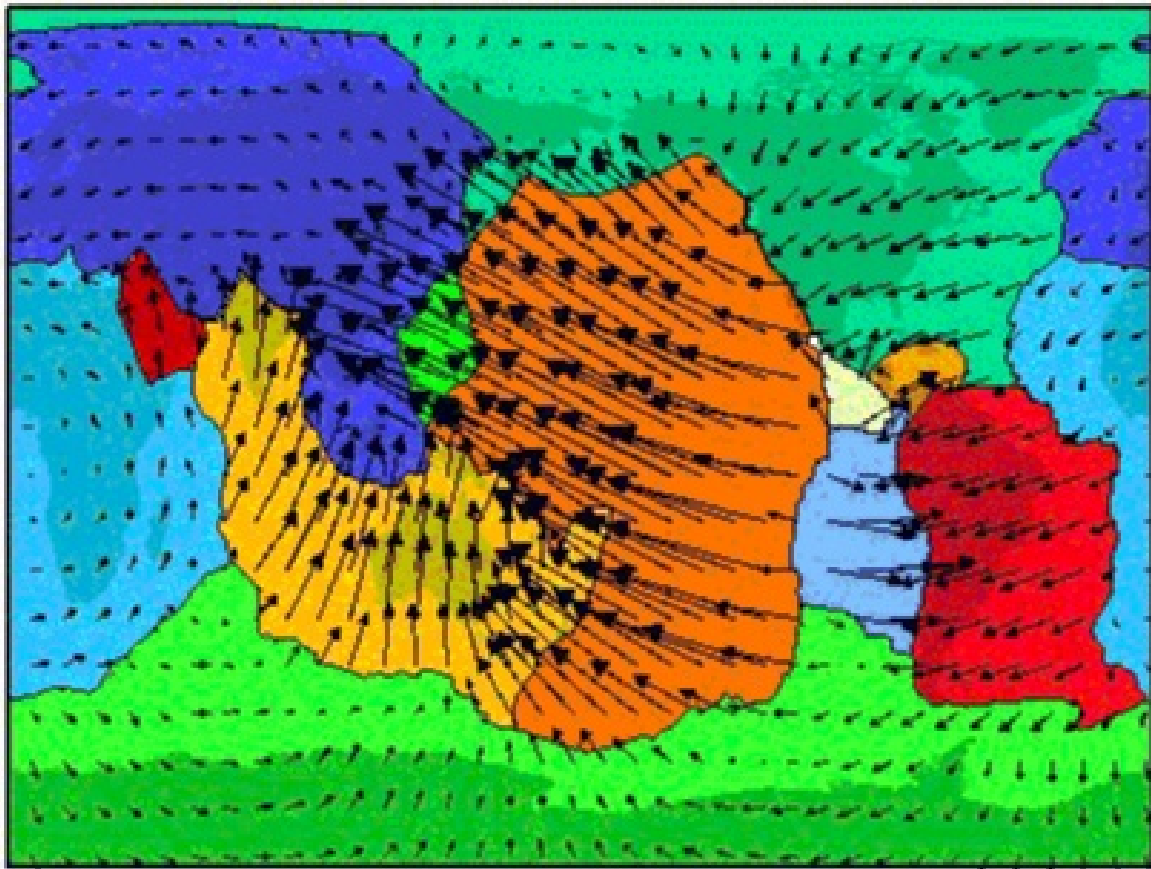
- Plate definition
- Plate motion : Euler pole
- Geological model : Nuvel-1A
- Geodetic model : ITRF
- Rigid plate rotations
- Plate deformation : strain and rotation tensors

World seismicity



2 The Earth surface is cut by «lines» of earthquakes, separating quite areas, i.e. plates.

Plate geometry and plate tectonics



Pacific

Eurasia

North America

South America

Africa

Antarctica

India-Australia

Nazca

Philippine

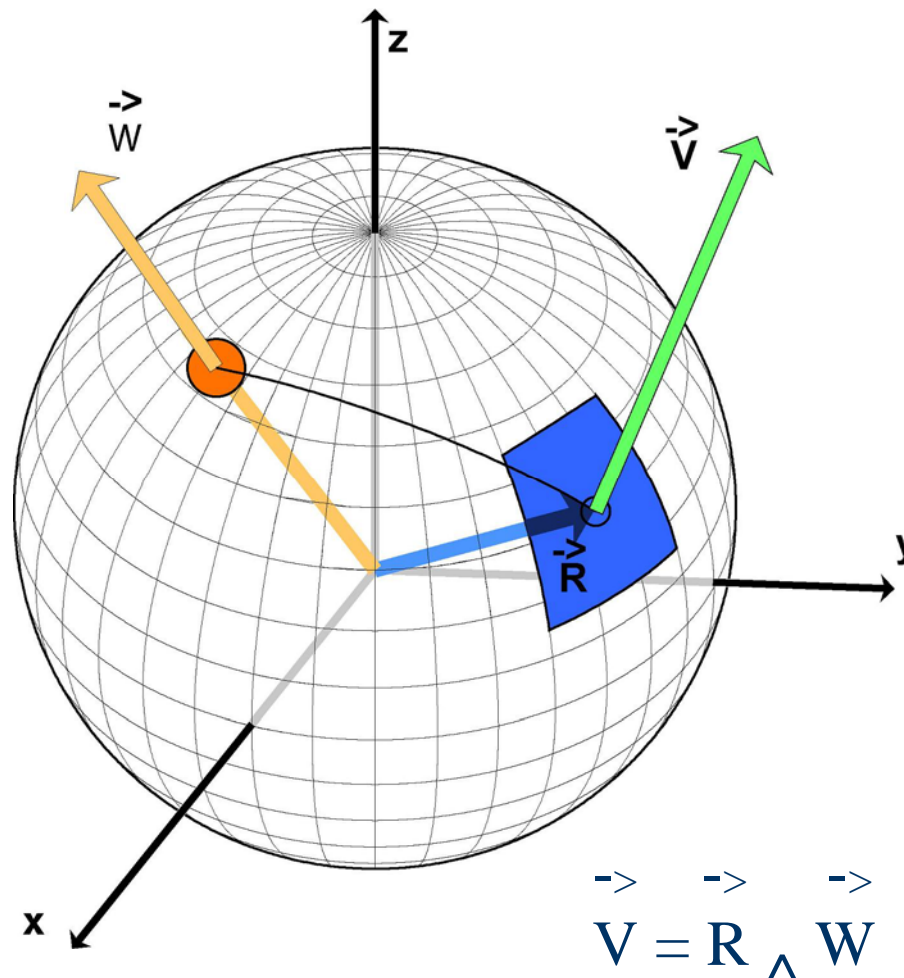
Arabia

Caraibe


Coco


There are 12 main plates and they move : it is **plate tectonics**

Rotation on a sphere

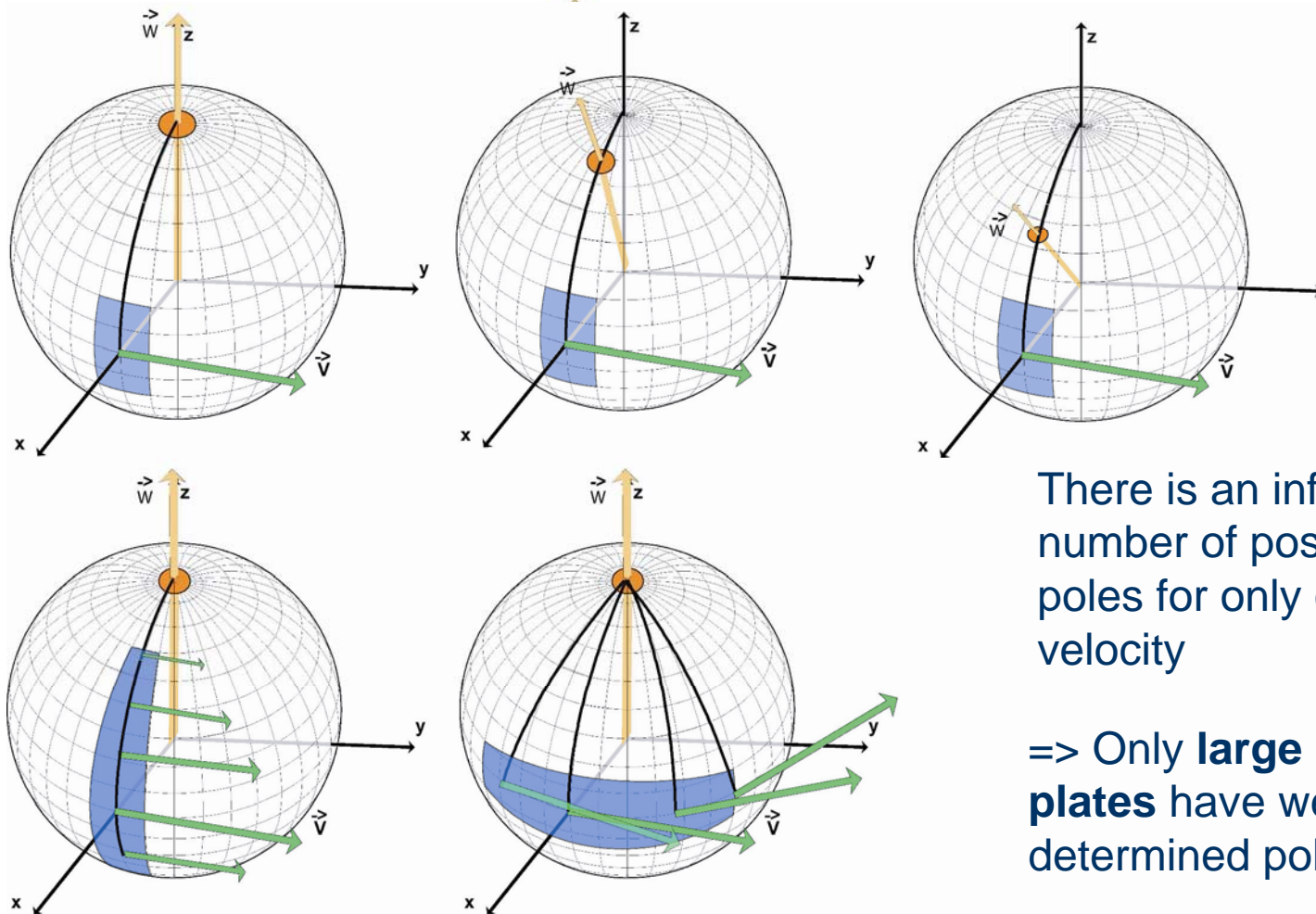


On a sphere, any translation at the surface is in fact a rotation about an axis crossing the Earth from its center to its surface.

The place at the surface where the axis points  is called the **rotation pole**

The amplitude of W  is called the **rotation speed**

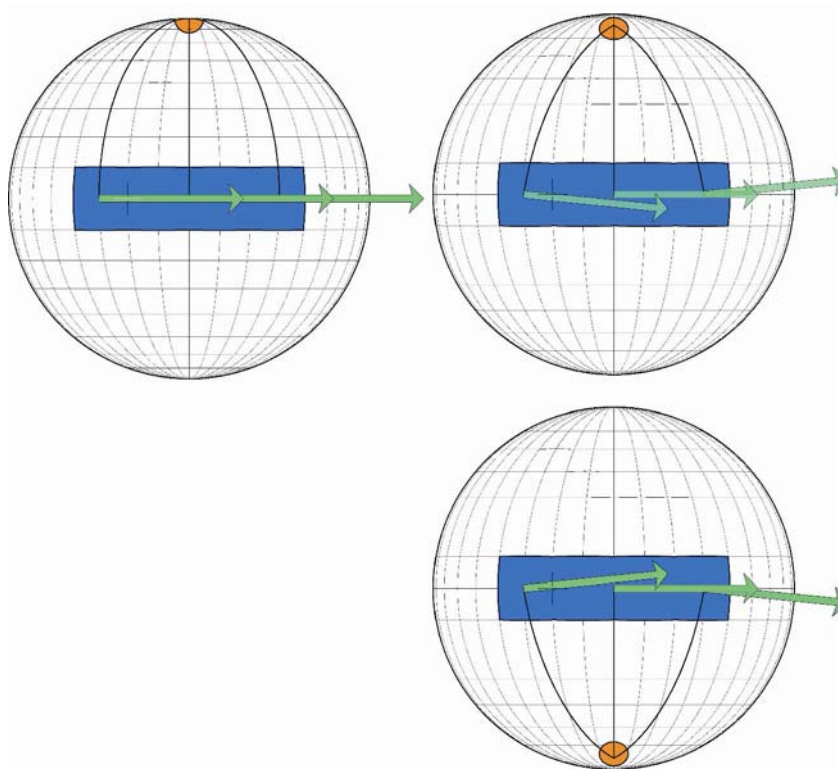
Finding a pole



There is an infinite number of possible poles for only one velocity

=> Only **large plates** have well determined poles

Effect of velocity uncertainty



Slightly different velocities can give very different poles

Or reverse :

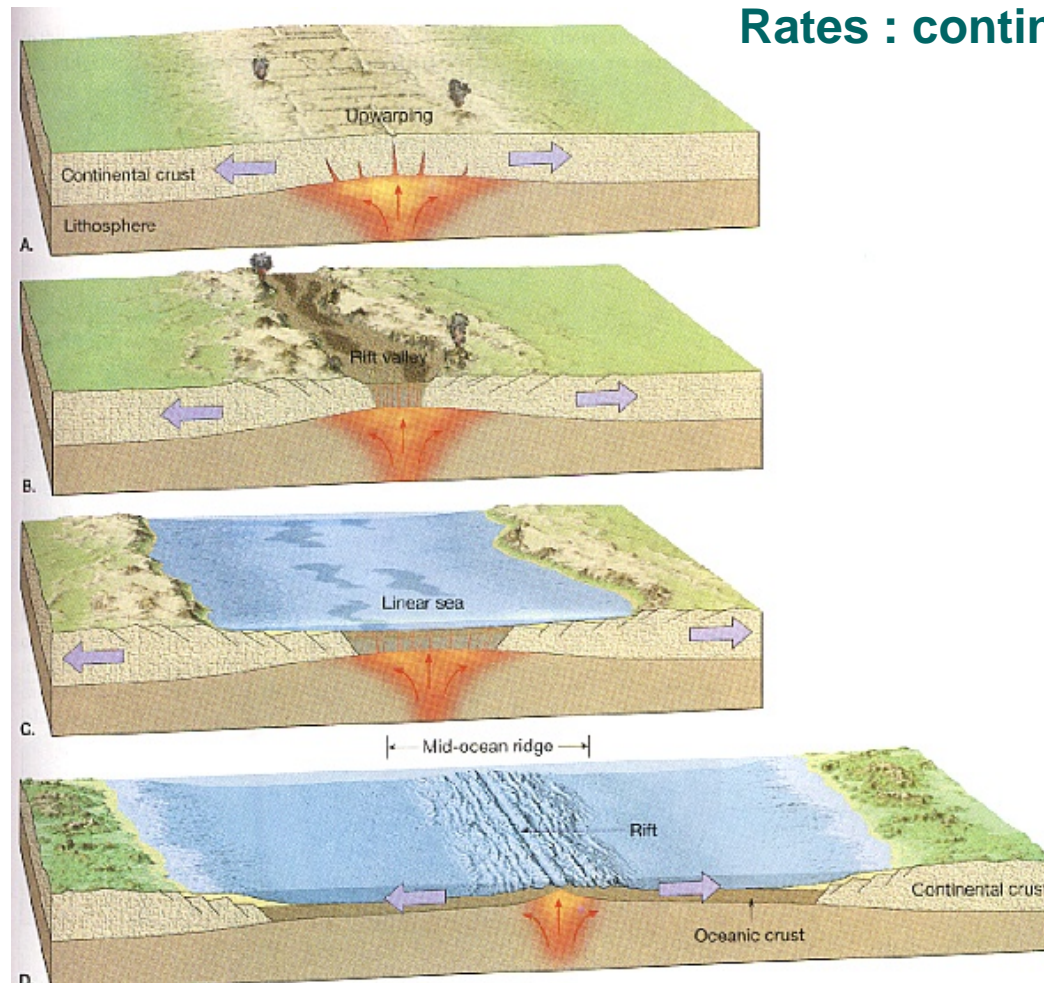
Very different poles can give quite similar velocities

Pole positions don't matter.

only velocities do !!!!

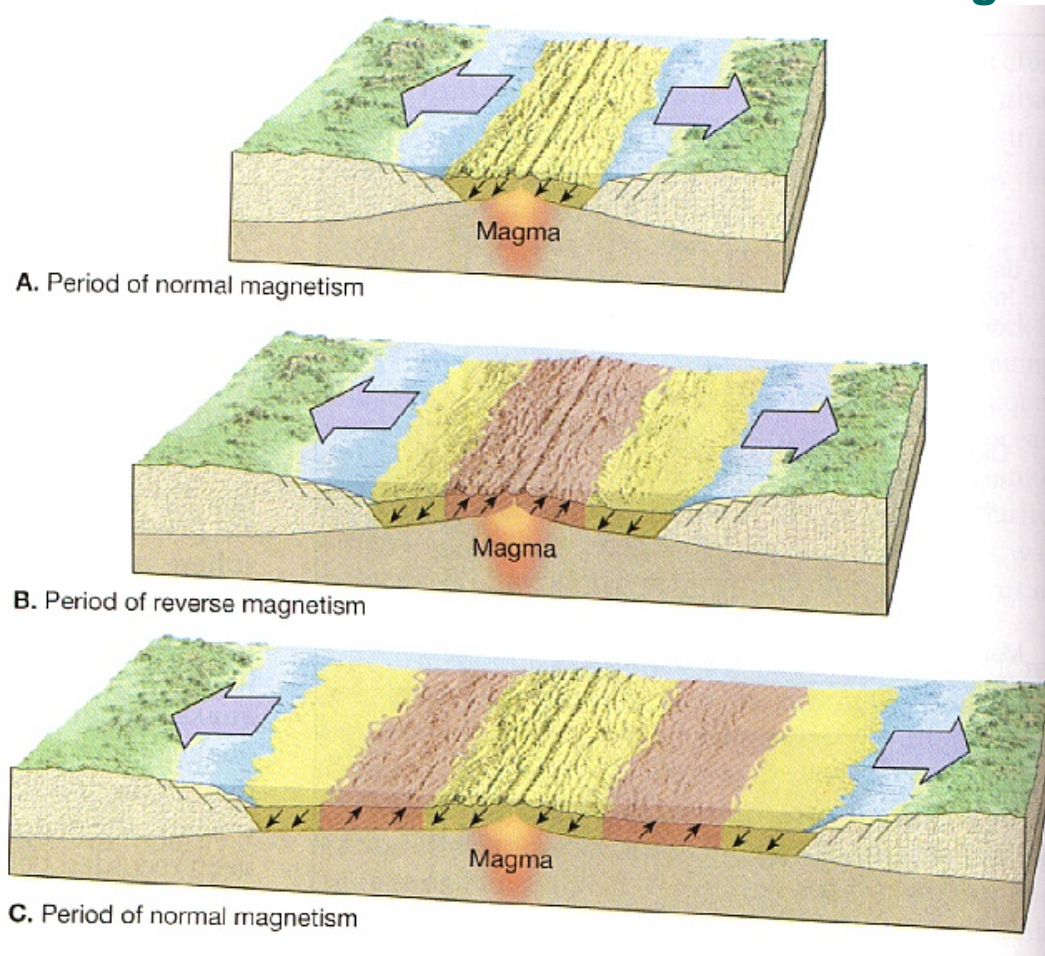
Geological model : how it works

Rates : continental drifting

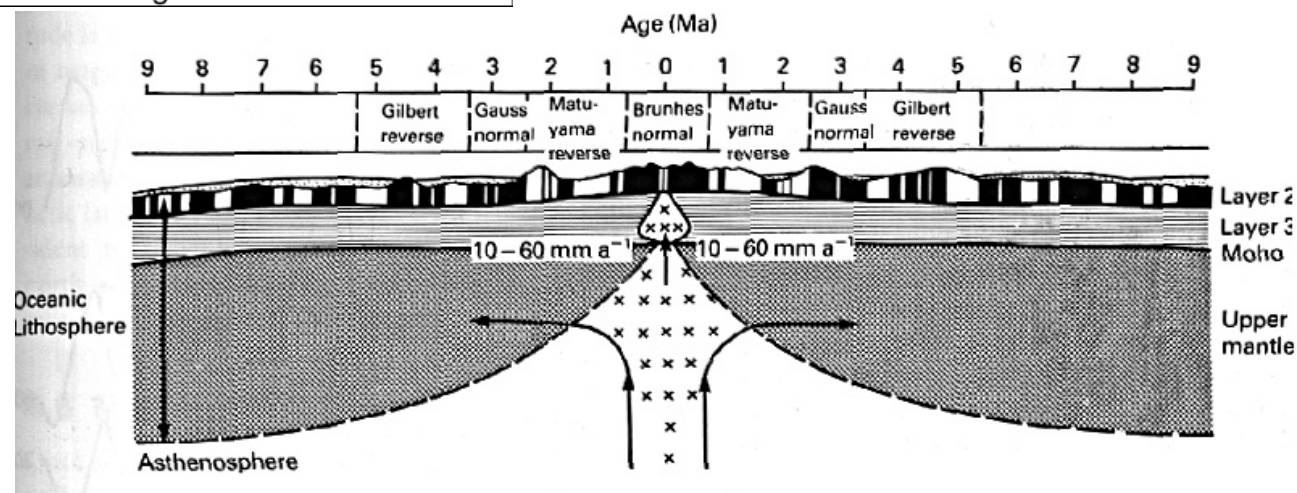
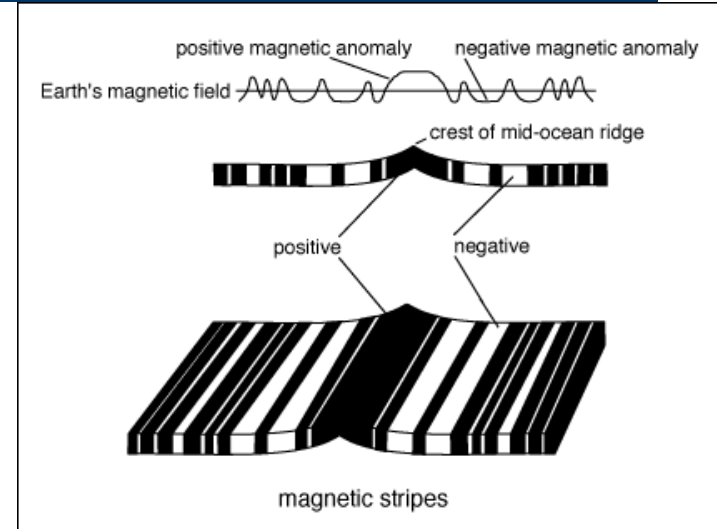
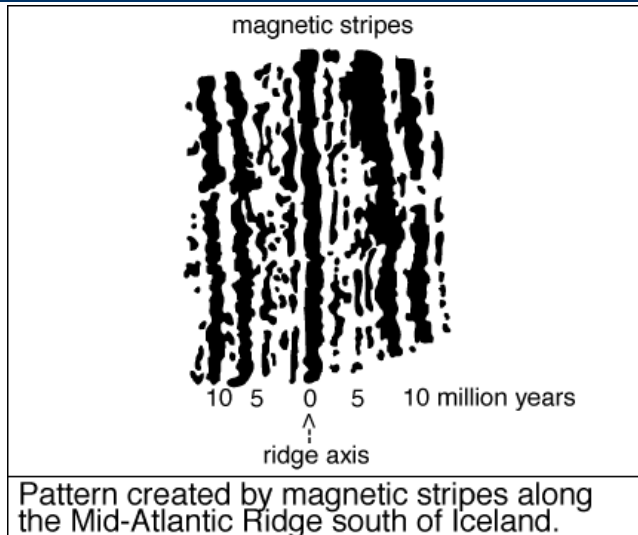


Geological model : how it works

Rates : generation of oceanic crust and sea floor magnetic anomalies



Rates : Vine and Matthews hypothesis



Rates : uncertainties from magnetic time scale

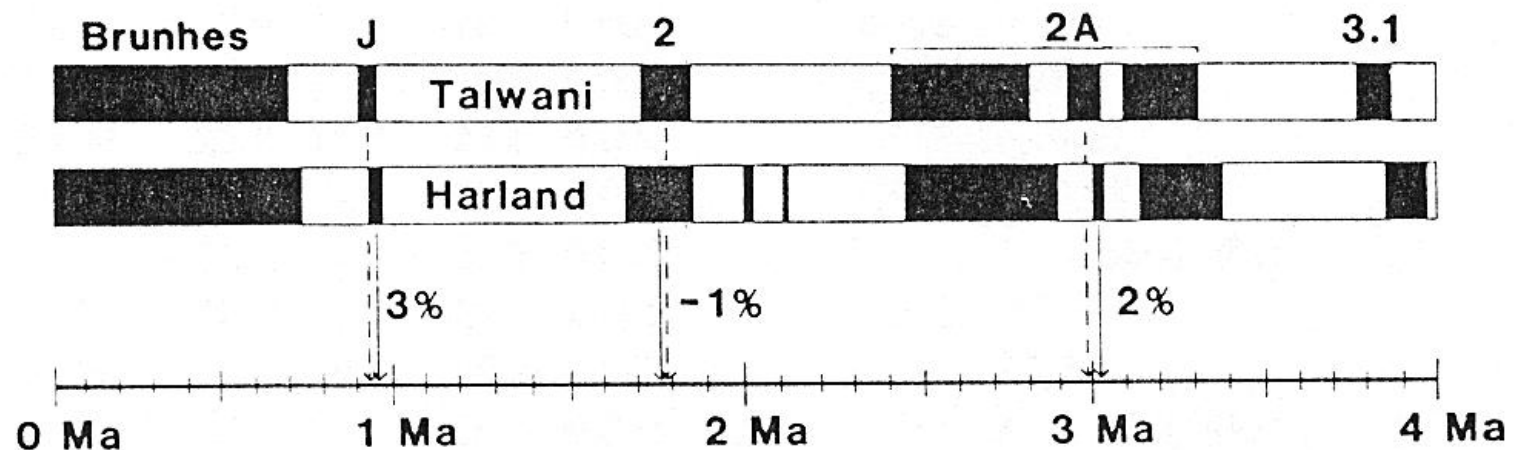


Figure 1. Comparison since 4.0 Ma of the geomagnetic reversal time-scale used here (Harland *et al.* 1982) with the time-scale used by Chase (1978) and Minster & Jordan (1978) (Talwani *et al.* 1971). We determined rates by seeking the best fit to the centre of anomaly 2A, which is 2 per cent older in the Harland *et al.* time-scale than in the Talwani *et al.* time-scale.

Geological model : how it works directions

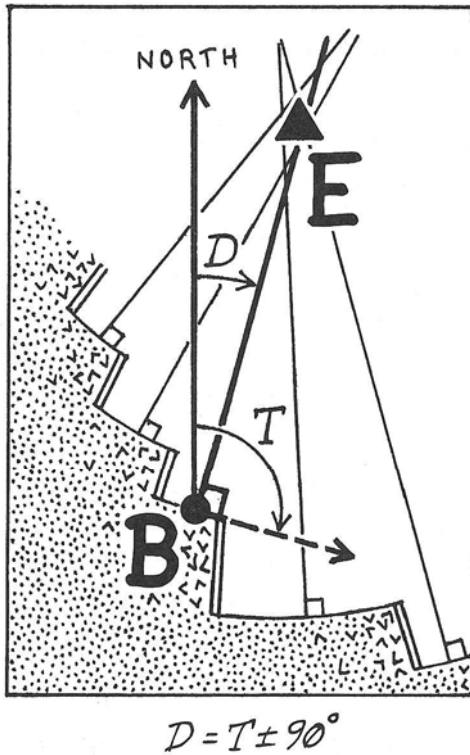


Figure 4-1. Locating an Euler pole **E** from the trends T of transforms. Lines nearly intersecting at **E** are great circles perpendicular to the transforms.

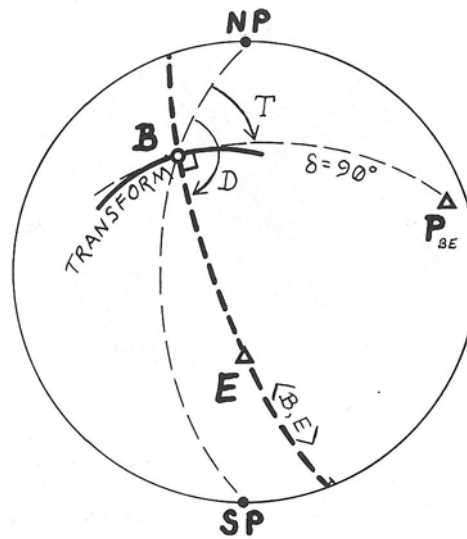


Figure 4-2. Euler pole **E** is on the great circle perpendicular to the trend of the transform. P_{BE} is the pole of the great circle $\langle B, E \rangle$.

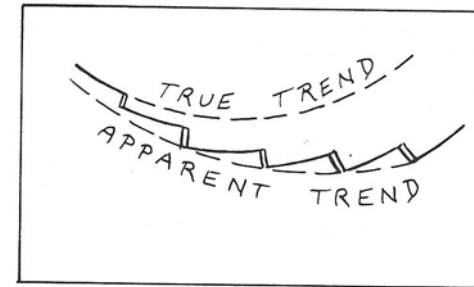
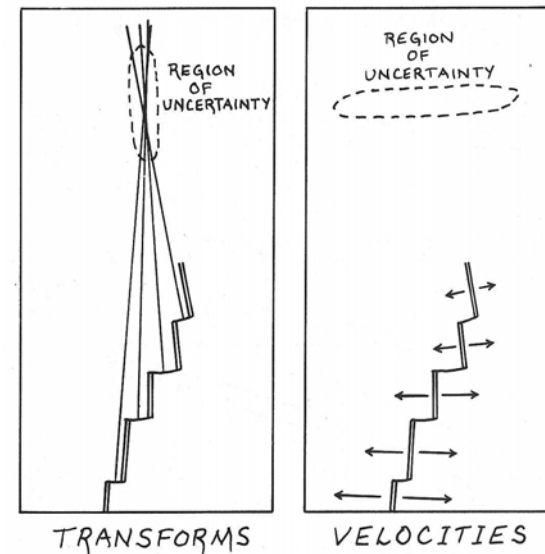


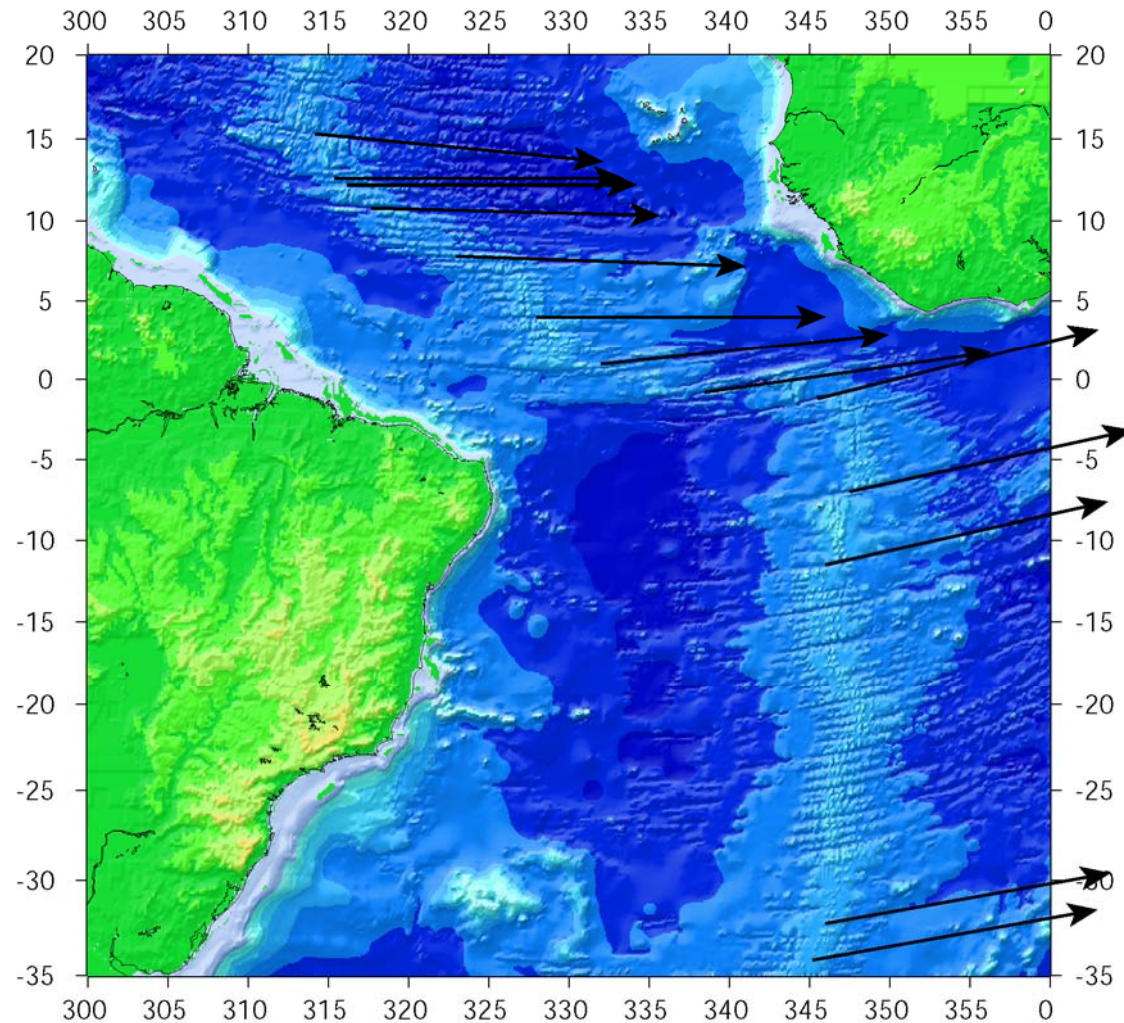
Figure 4-3. Apparent and true trends of transform system offset by short ridge segments.



Geological model : real data

Transform faults azimuths

Lon	lat	azimuth
15.3	-45.8	95.5
12.6	-44.6	90.0
12.2	-43.8	90.0
10.8	-42.3	91.5
7.8	-37.0	92.0
4.0	-32.0	90.0
1.0	-28.0	84.0
-0.8	-21.5	82.0
-1.2	-14.5	76.0
-7.0	-12.5	77.7
-11.5	-14.0	77.5
-32.3	-14.0	80.0
-34.2	-14.8	80.0
-54.2	-2.0	65.0

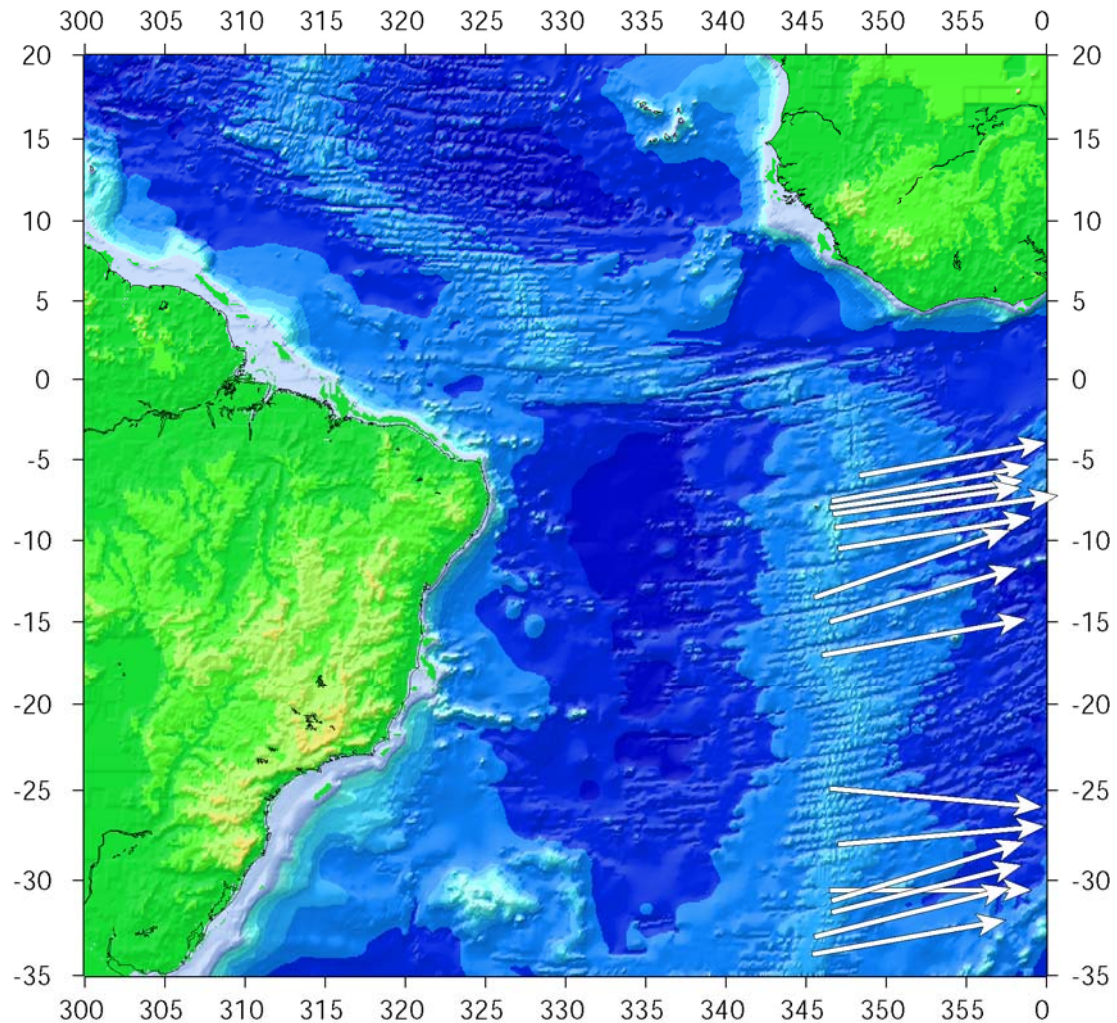


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Geological model : real data

Spreading rates

lon, lat, rate, az
-6.0 -11.7 33 10
-7.6 -13.4 35 10
-8.0 -13.5 34 8
-8.4 -13.3 33 8
-9.2 -13.2 39 8
-10.5 -13.0 34 9
-13.5 -14.5 36 19
-15.0 -13.5 34 16
-17.0 -14.0 36 10
-24.9 -13.5 37 -5
-28.0 -13.0 36 5
-30.5 -13.5 35 0
-31.1 -13.2 35 17
-31.7 -13.4 34 14
-33.0 -14.5 35 14
-33.9 -14.6 34 10
-38.5 -17.0 36 10
-40.0 -16.0 36 5
-42.0 -16.0 32 5
-43.0 -16.0 35 5
-54.2 -1.3 28 25
-54.5 -1.1 30 25



GS of CAS – Geodesy & Geodynamics – Beijing June 2004

Geological model : real data

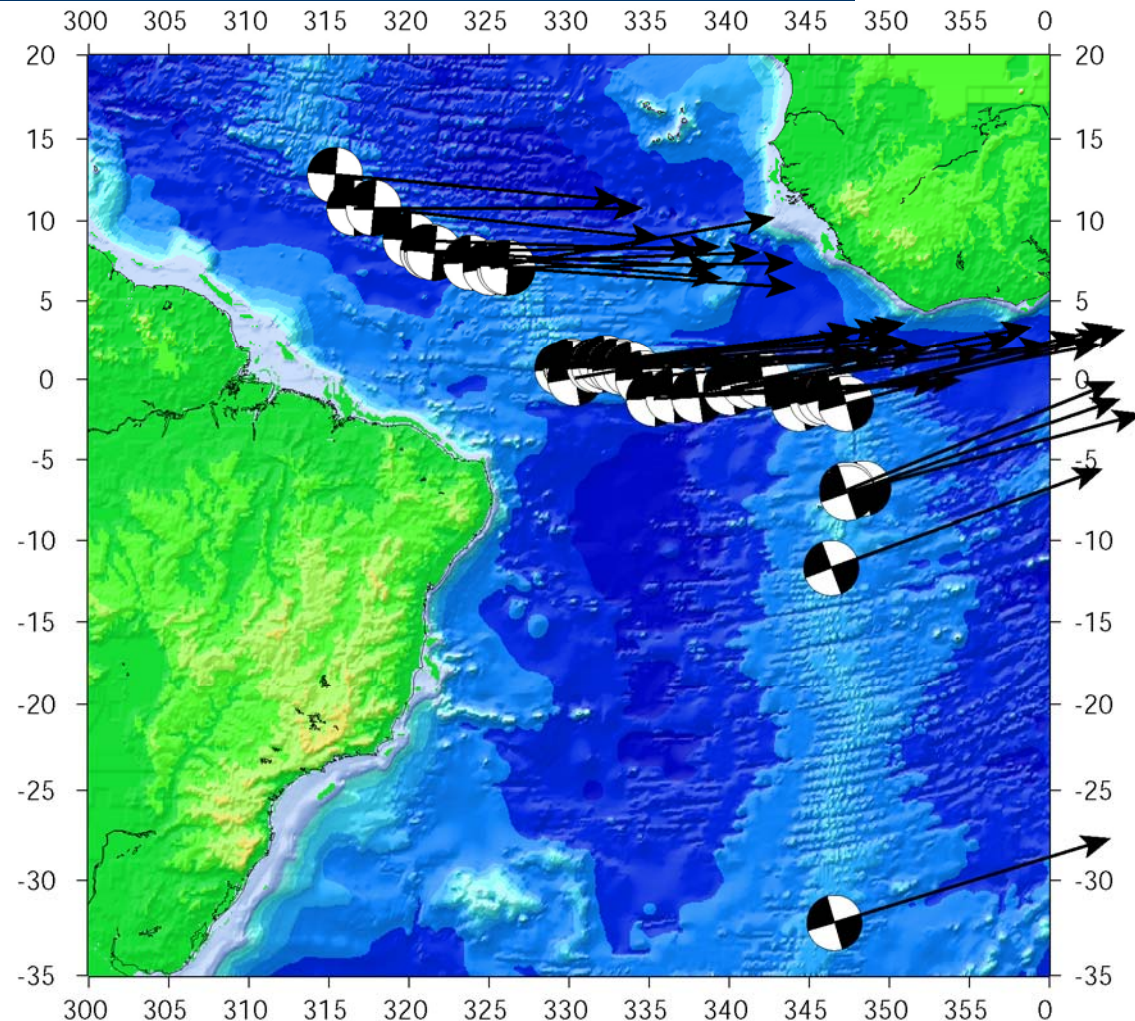
Slip vector azimuths

Lon lat azimuth

12.8 -44.6 95.0
 10.8 -43.4 90.0
 10.8 -42.2 96.0
 8.8 -39.9 92.0
 8.1 -38.8 93.0
 8.1 -38.5 89.0
 8.0 -38.4 95.0
 7.4 -36.1 88.0
 7.1 -34.9 80.0
 7.1 -34.0 89.0
 7.1 -33.8 94.0
 0.7 -30.4 84.0
 0.9 -29.9 83.0
 0.8 -29.8 88.0
 0.8 -29.7 87.0
 0.1 -29.6 80.0
 0.9 -28.4 88.0
 0.9 -28.1 82.0
 1.1 -27.7 85.0
 0.9 -27.1 85.0
 0.9 -27.1 82.0
 0.9 -26.8 85.0
 0.8 -26.8 81.0
 0.7 -26.1 88.0
 0.1 -25.3 84.0
 -1.2 -24.7 87.0
 -1.0 -23.5 87.0
 -1.0 -21.9 81.0

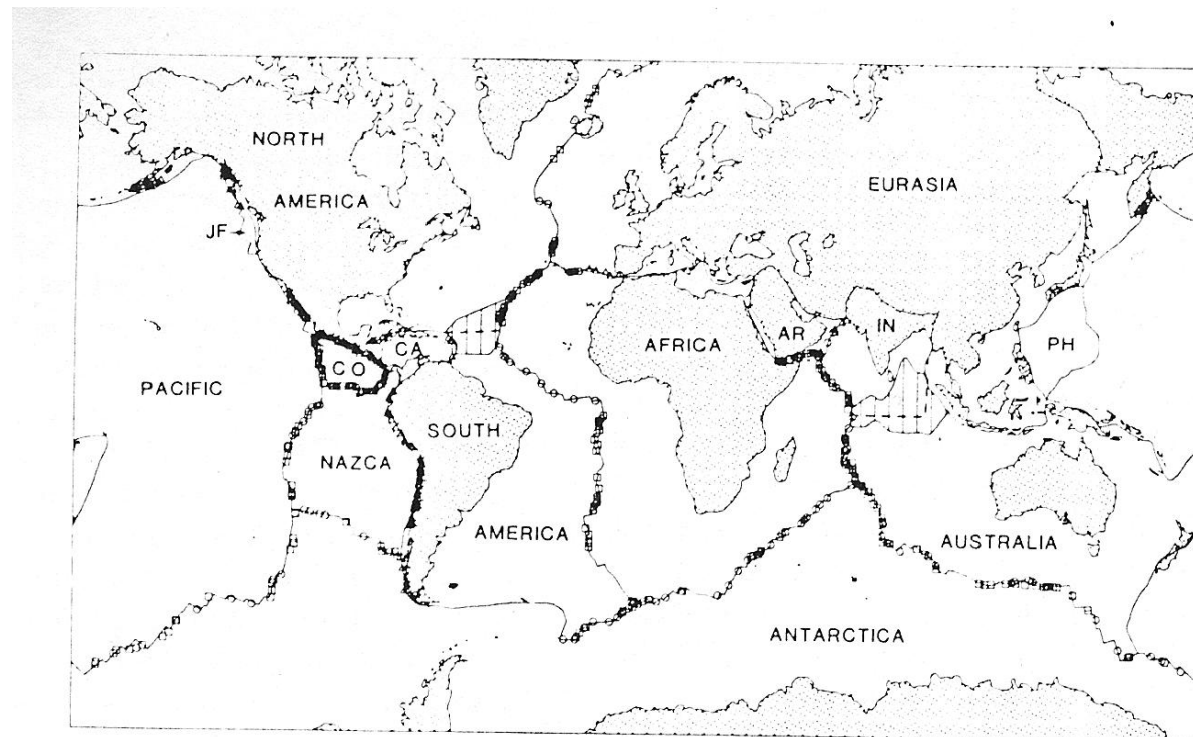
Lon lat azimuth

-0.5 -19.9 80.0
 -0.1 -18.8 79.0
 -0.0 -17.9 83.0
 -1.5 -15.6 76.0
 -1.2 -14.5 79.0
 -1.1 -14.0 77.0
 -1.0 -13.5 76.0
 -1.5 -12.7 75.0
 -6.8 -11.6 75.0
 -6.9 -12.6 68.0
 -7.1 -12.6 71.0
 -11.7 -13.6 70.0
 -32.2 -13.4 73.0
 -35.8 -16.0 76.0
 -35.5 -16.1 81.0
 -47.6 -12.9 76.0
 -46.9 -10.8 85.0



Geological model : Nuvel-1A, Demets et al., 1990

Current plate motions, Geophys. Journal. Int., 101, 425-478, 1990



Around 1200 slip vector azimuth, transform fault orientations and spreading rates are compiled in one model for plate motion

Geological model : data table

Table 3. (continued)

26.90 -44.50 26 4	24.5 0.022 n16c	Rabinowitz & Schouten (1985)	4.00 -32.00 90.0 5	86.0 0.016	Emery & Uchupi (1984)
26.20 -44.80 22 3	23.5 0.037 n30c	McGregor et al. (1977)	1.00 -28.00 84.0 5	84.1 0.015	Emery & Uchupi (1984)
25.70 -45.00 24 4	24.2 0.022 n24c	Rabinowitz & Schouten (1985)	-0.80 -21.50 82.0 2	81.0 0.110	Ballarín et al. (1984)
25.30 -45.40 22.5 2	24.4 0.089 n26c	Rabinowitz & Schouten (1985)	-1.20 -14.50 76.0 3	77.8 0.069	Emery & Uchupi (1985)
25.10 -45.40 24.5 2	24.4 0.090 n26c	Rona & Gray (1980)	-7.00 -12.50 77.7 2	77.3 0.150	Brosena (1986)
24.50 -46.10 23 4	24.6 0.023 n23c	Rabinowitz & Schouten (1985)	-11.50 -14.00 77.5 3	78.2 0.056	D. Forsyth
24.20 -46.30 24.5 2	25.1 0.097 n15c	Rona & Gray (1980)	-32.30 -14.00 80.0 2	78.5 0.098	(personal communication, 1985)
23.00 -45.00 25 4	25.2 0.025 n08c	Rabinowitz & Schouten (1985)	-34.20 -14.80 80.0 3	78.8 0.042	Sclater et al. (1976a)
22.80 -45.00 25 2	25.1 0.100 n08c	Rabinowitz & Schouten (1985)	-54.20 -2.00 65.0 10	71.0 0.006	
Africa-North America: Transform Axiomatics					
35.20 -35.60 104.5 2	103.6 0.203	Roast et al. (1984)			
33.70 -38.70 104.5 2	103.4 0.216	Roast et al. (1984)			
30.00 -42.40 101.5 3	102.9 0.100	Roast et al. (1984) & Pockley et al. (1988)			
23.70 -45.70 98.0 2	102.2 0.220				
Africa-North America: Slip Vectors					
35.43 -36.03 102.0 20	103.6 0.002	CMT 4.20.85			
35.41 -36.01 101.0 10	103.7 0.008	CMT 6.06.82			
35.35 -36.08 100.0 10	103.7 0.008	Bergman & Solomon (1988)			
35.14 -35.45 101.0 15	103.6 0.004	CMT 7.14.80			
33.79 -38.64 101.0 10	103.4 0.009	Bergman & Solomon (1988)			
33.78 -38.66 102.0 15	103.4 0.004	CMT 5.07.84			
33.69 -38.60 103.0 15	103.4 0.004	CMT 5.03.84			
28.74 -43.58 91.0 20	102.8 0.002	Engeln et al. (1986)			
23.83 -45.94 100.0 10	102.2 0.009	Bergman & Solomon (1988)			
23.86 -45.57 100.0 10	102.2 0.009	Bergman & Solomon (1988)			
23.81 -45.44 106.0 15	102.2 0.004	CMT 11.28.81			
23.74 -45.17 102.0 15	102.2 0.004	CMT 3.12.77			
Africa-Eurasia: Transform Axiomatics					
36.90 -23.50 257.0 5	260.2 0.187	Loughon et al. (1972)			
37.00 -22.60 265.0 3	263.3 0.399	Loughon et al. (1972)			
37.10 -21.70 265.0 3	266.3 0.384	Loughon et al. (1972)			
37.10 -20.50 -90.0 7	270.4 0.098	Loughon et al. (1972)			
Africa-Eurasia: Slip Vectors					
37.75 -17.25 -89.0 25	-79.2 0.022	CMT 10.17.83			
37.22 -14.93 -50.0 25	-71.5 0.042	Grimison & Chen (1986)			
36.96 -11.84 267.0 25	-62.0 0.066	Grimison & Chen (1986)			
36.01 -10.57 -35.0 25	-57.0 0.092	Fukao (1973)			
35.99 -10.34 -60.0 25	-56.3 0.098	Grimison & Chen (1986)			
36.23 -7.61 -35.0 25	-49.8 0.104	Grimison & Chen (1986)			
Africa-South America: Spreading Rates					
-6.00 -11.70 33 6	34.1 0.018 n10w	van Andel et al. (1973)			
-7.60 -13.40 35 6	34.4 0.018 n10w	van Andel et al. (1973)			
-8.00 -13.50 34 2	34.4 0.160 n08w	Brosena (1986)			
-8.40 -13.30 33 6	34.5 0.018 n08w	van Andel et al. (1973)			
-9.20 -13.20 39 6	34.6 0.017 n08w	van Andel et al. (1973)			
-10.50 -13.00 34 3	34.8 0.068 n09w	Brosena (1986)			
-13.50 -14.50 36 4	35.0 0.034 n19w	Brosena (1986)			
-15.00 -13.50 34 2	35.4 0.136 n16w	Brosena (1986)			
-17.00 -14.00 36 3	35.6 0.061 n10w	Brosena (1986)			
-24.90 -13.50 37 6	34.5 0.013 n05e	Dickson et al. (1968)			
-28.00 -13.00 36 3	35.7 0.053 n05w	Dickson et al. (1968)			
-30.50 -13.50 35 3	35.1 0.051 n00c	Dickson et al. (1968)			
-31.10 -13.40 35 5	35.7 0.019 n17w	Welch et al. (1986)			
-31.70 -13.40 34 3	35.7 0.002 n14w	Welch et al. (1986)			
-33.00 -14.50 35 3	35.6 0.051 n14w	Welch et al. (1986)			
-33.90 -14.60 34 4	35.6 0.029 n10w	Welch et al. (1986)			
-38.50 -17.00 36 6	35.1 0.013 n10w	Dickson et al. (1968)			
-40.00 -16.00 36 3	34.7 0.051 n05w	Loomis & Morgan (1973)			
-42.00 -16.00 32 4	34.4 0.029 n05w	Dickson et al. (1968)			
-43.00 -16.00 35 3	34.2 0.052 n05w	Loomis & Morgan (1973)			
-54.20 -1.30 28 5	30.9 0.023 n25w	NGDC Chain 115-4			
-54.50 -1.10 30 3	30.8 0.064 n25w	NGDC Chain 115-4			
-54.60 -1.00 30 5	30.8 0.023 n25w	NGDC Chain 115-4			
Africa-South America: Transform Axiomatics					
15.30 -45.80 95.5 3	94.0 0.128	Roast et al. (1984)			
12.60 -44.60 90.0 3	93.1 0.108	Collette et al. (1979)			
12.20 -43.80 90.0 3	92.6 0.101	Collette et al. (1979)			
10.80 -42.30 91.5 2	91.7 0.197	Maconald et al. (1986)			
7.80 -37.00 92.0 8	88.6 0.008	Emery & Uchupi (1984)			
4.00 -32.00 90.0 5	86.0 0.016				
1.00 -28.00 84.0 5	84.1 0.015				
-0.80 -21.50 82.0 2	81.0 0.110				
-1.20 -14.50 76.0 3	77.8 0.069				
-7.00 -12.50 77.7 2	77.3 0.150				
-11.50 -14.00 77.5 3	78.2 0.056				
-32.30 -14.00 80.0 2	78.5 0.098				
-34.20 -14.80 80.0 3	78.8 0.042				
-54.20 -2.00 65.0 10	71.0 0.006				
Africa-South America: Slip Vectors					
15.34 -45.92 97.0 10	94.1 0.012	Bergman & Solomon (1988)			
15.30 -45.78 98.0 10	94.0 0.011	Bergman & Solomon (1988)			
15.25 -45.15 97.0 10	93.6 0.011	Bergman & Solomon (1988)			
14.14 -45.18 100.0 20	93.6 0.003	Engeln et al. (1986)			
12.84 -44.57 95.0 15	93.1 0.004	CMT 6.09.87			
12.05 -43.79 101.0 20	92.6 0.002	Engeln et al. (1986)			
10.79 -43.51 92.0 10	92.4 0.009	Bergman & Solomon (1988)			
10.83 -43.43 90.0 10	92.4 0.008	CMT 1.10.85			
10.83 -43.23 96.0 20	92.2 0.002	Engeln et al. (1986)			
10.77 -43.11 92.0 10	92.2 0.008	Bergman & Solomon (1988)			
10.79 -42.23 96.0 15	91.7 0.003	CMT 3.20.84			
10.72 -42.02 97.0 20	91.5 0.002	Engeln et al. (1986)			
10.72 -41.68 87.0 10	91.3 0.008	Bergman & Solomon (1988)			
8.80 -39.87 92.0 15	90.3 0.003	CMT 1.33.80			
8.05 -38.79 102.0 20	89.6 0.001	CMT 11.28.81			
8.15 -38.76 93.0 10	89.6 0.006	CMT 11.01.84			
8.10 -38.55 89.0 15	89.5 0.003	CMT 11.05.78			
8.04 -38.39 95.0 15	89.4 0.003	CMT 12.06.81			
8.11 -38.09 90.0 10	89.3 0.006	Engeln et al. (1986)			
7.39 -36.10 88.0 15	88.1 0.002	CMT 4.22.81			
7.30 -34.86 85.0 10	87.4 0.005	Engeln et al. (1986)			
7.08 -34.87 80.0 15	87.5 0.002	CMT 12.24.85			
7.10 -34.04 89.0 15	87.0 0.002	CMT 7.26.80			
7.07 -33.85 94.0 20	86.9 0.001	CMT 8.30.84			
6.67 -30.39 84.0 15	85.3 0.002	CMT 6.22.84			
0.86 -29.88 83.0 10	85.0 0.004	CMT 10.12.85			
0.83 -29.82 88.0 10	85.0 0.004	CMT 3.20.78			
0.77 -29.69 87.0 10	84.9 0.004	CMT 3.20.78			
0.11 -29.60 80.0 20	84.9 0.001	CMT 17.4.80			
0.82 -28.98 90.0 20	84.6 0.001	Engeln et al. (1986)			
0.95 -28.43 88.0 10	84.3 0.004	CMT 6.06.85			
0.97 -28.29 89.0 20	84.2 0.001	Engeln et al. (1986)			
0.93 -28.09 82.0 15	84.1 0.002	CMT 19.9.84			
1.14 -27.71 85.0 15	83.9 0.002	CMT 6.22.78			
0.89 -27.11 85.0 15	83.6 0.002	CMT 11.14.79			
0.95 -27.08 82.0 15	83.6 0.002	CMT 11.02.81			
0.93 -26.83 85.0 15	83.5 0.002	CMT 4.22.85			
0.80 -26.77 81.0 15	83.5 0.002	CMT 6.15.86			
0.90 -26.77 88.0 20	83.4 0.001	Engeln et al. (1986)			
0.87 -26.50 88.0 20	83.3 0.001	Engeln et al. (1986)			
0.75 -26.14 88.0 20	83.1 0.001	CMT 3.23.86			
0.81 -25.45 89.0 20	82.8 0.001	Engeln et al. (1986)			
0.11 -25.35 84.0 10	82.8 0.004	CMT 11.01.80			
-1.19 -24.68 87.0 10	82.5 0.004	CMT 8.12.82			
-1.30 -24.30 99.0 20	82.4 0.001	Engeln et al. (1986)			
-0.99 -23.48 87.0 15	81.9 0.002	CMT 12.08.84			
-0.85 -22.13 85.0 20	81.3 0.001	Engeln et al. (1986)			
-0.97 -21.86 81.0 10	81.2 0.004	CMT 1.03.82			
-0.84 -21.81 77.0 10	81.1 0.004	CMT 10.13.83			
-0.51 -19.92 80.0 15	80.2 0.002	CMT 12.29.86			
-0.50 -19.90 80.0 20	80.2 0.001	Engeln et al. (1986)			
-0.52 -19.86 77.0 10	80.2 0.005	CMT 5.05.87			
-0.58 -19.77 83.0 15	80.1 0.002	CMT 10.09.84			
-0.38 -19.55 80.0 15	80.0 0.002	CMT 6.04.85			
-0.22 -19.19 79.0 15	79.8 0.002	CMT 6.07.87			
-0.32 -19.17 83.0 20	79.8 0.001	Engeln et al. (1986)			
-0.04 -19.14 77.0 10	79.8 0.005	CMT 5.05.87			
-0.13 -18.83 79.0 10	79.6 0.005	CMT 7.07.81			
-0.30 -18.60 88.0 20	79.6 0.001	Engeln et al. (1986)			
-0.14 -18.24 74.0 15	79.4 0.002	CMT 3.12.87			
-0.19 -18.03 89.0 20	79.3 0.001	Engeln et al. (1986)			
-0.02 -17.88 83.0 10	79.2 0.005	CMT 6.24.86			

Arabia-India: Fault Trends

21.00	61.80	30.0	5	27.8	0.459
18.00	60.20	23.0	5	22.3	0.534

Matthews (1966)
Matthews (1966)

Arabia-India: Slip Vectors

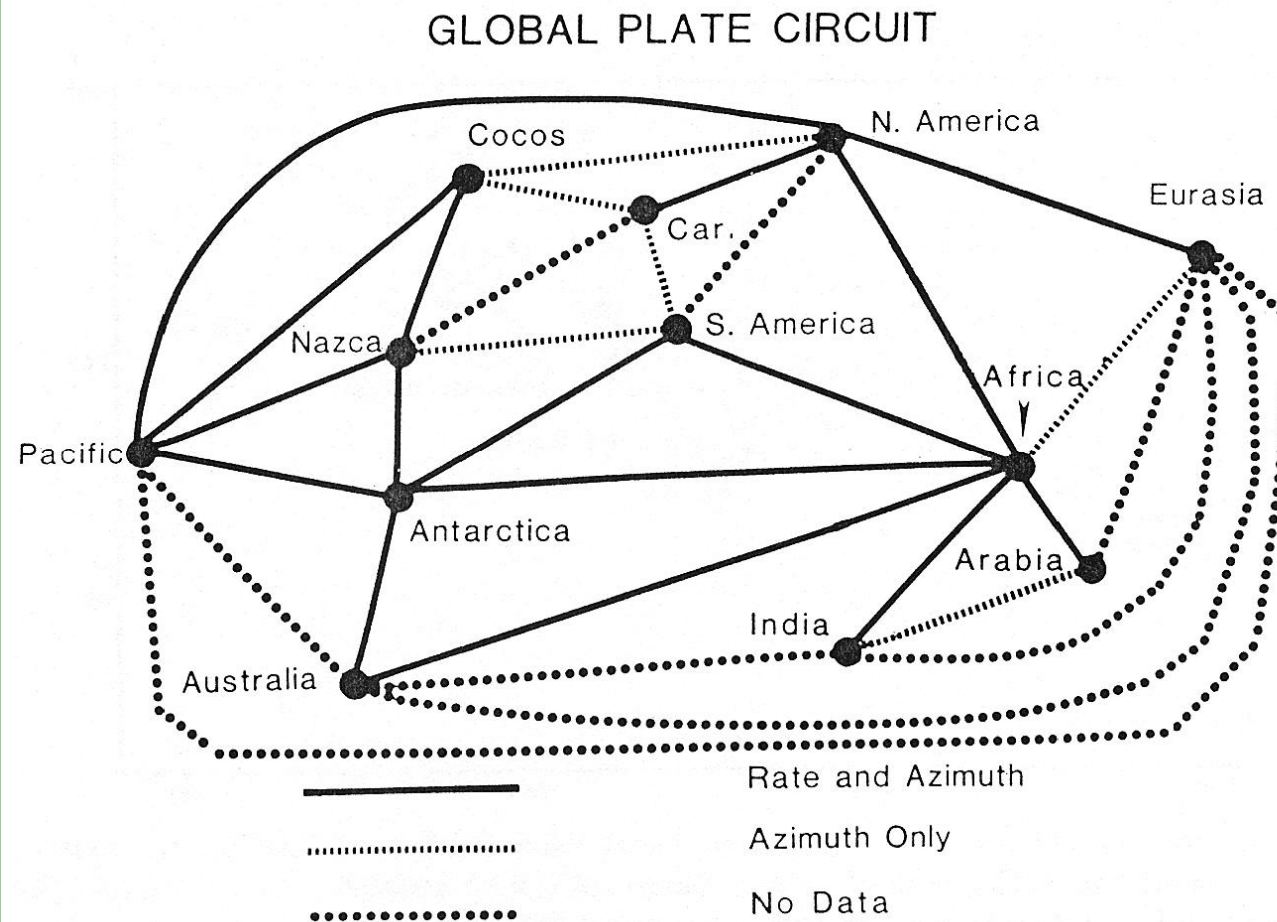
24.58	66.23	41.0	15	37.5	0.270
23.79	64.73	28.0	15	34.6	0.176
21.87	62.32	12.0	15	29.5	0.067
20.91	62.44	26.0	15	28.3	0.055
14.94	57.96	23.0	15	16.4	0.171
14.57	58.09	10.0	15	16.0	0.188

Quittmeyer & Kafka (1984)
Quittmeyer & Kafka (1984)
Quittmeyer & Kafka (1984)
CMT 4.7.85
CMT 12.14.85
CMT 12.5.81

The motion on some pairs of plates are well constrained because they have oceanic boundaries (e.g. Africa/South America).

Others are poorly known (e.g. Arabia/India)

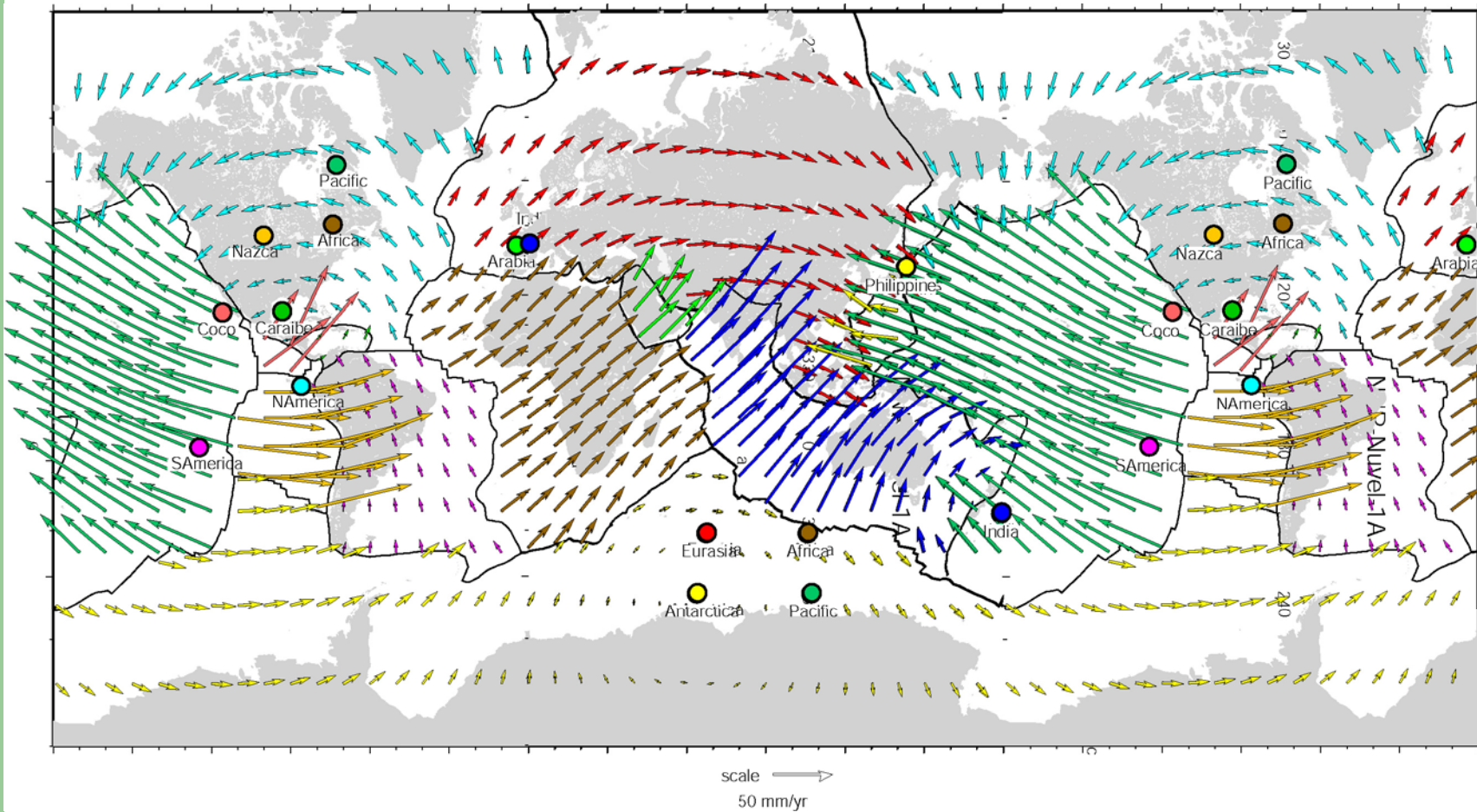
Geological model : closure circuit



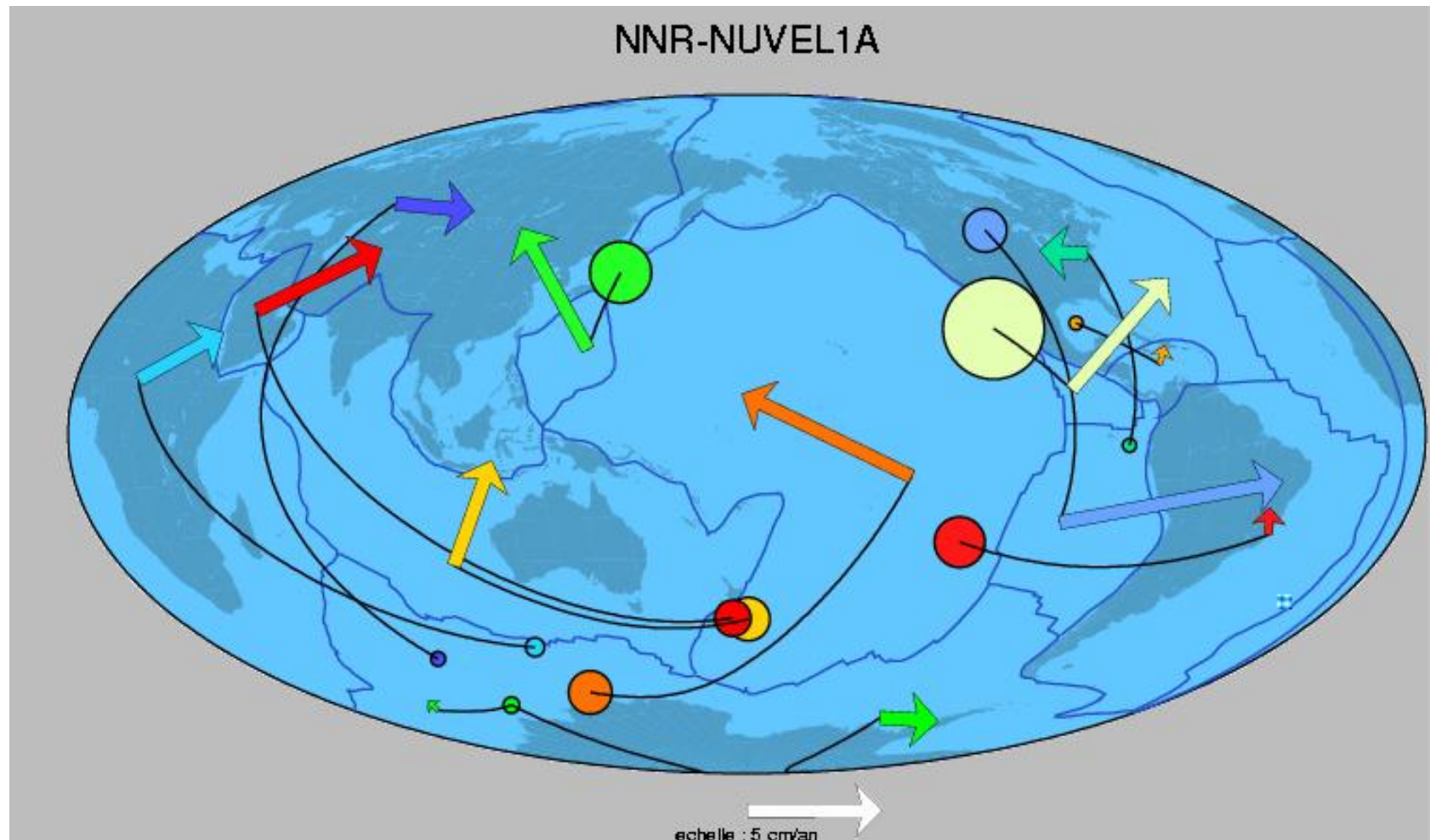
The relative motion of pairs of plate **without data** can be determined through a **circuit** of pairs of plates with data. (e.g. India/Australia is known through Africa, or India/Eurasia through Africa and North America)

The result is of course less well constrained

NNR-Nuvel-1A : velocities

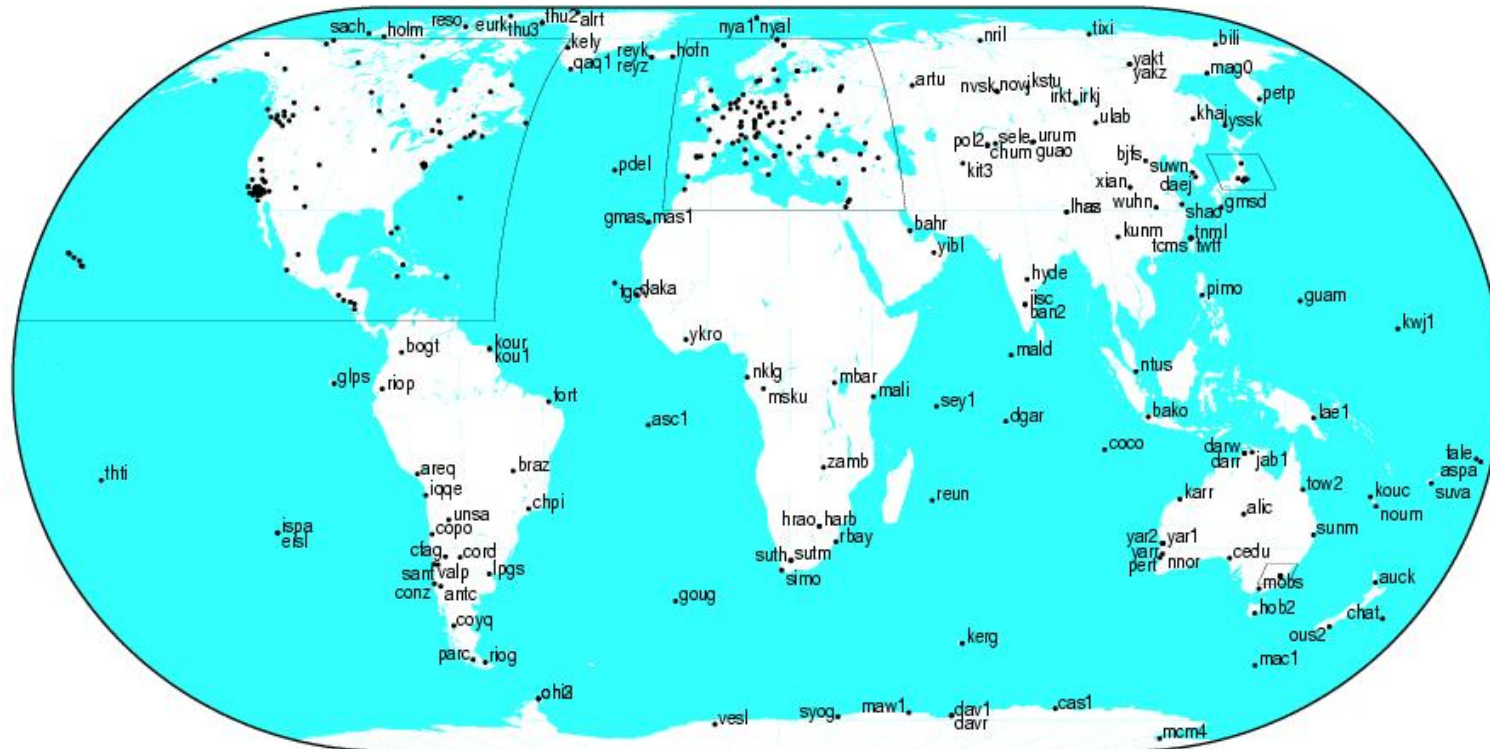


NNR-Nuvel-1A : rotation poles



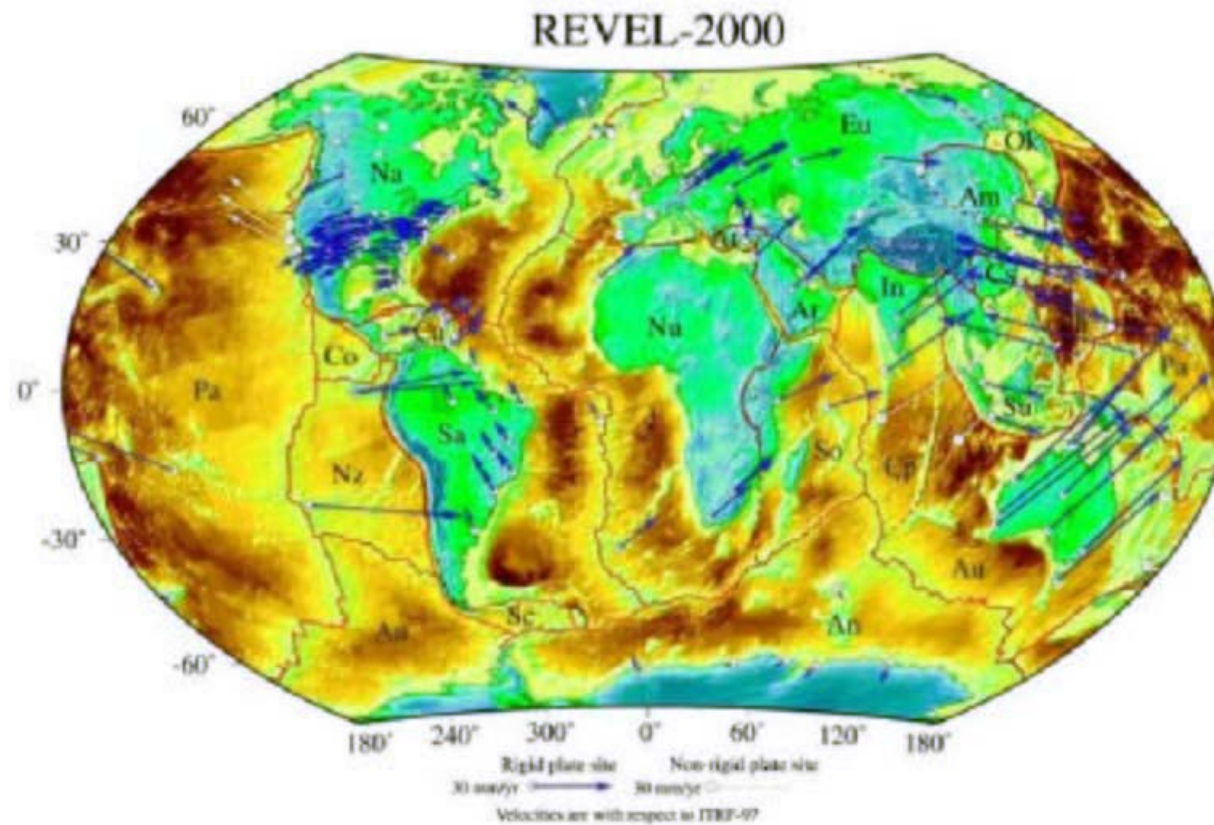
IGS network

IGS Tracking Network : <http://igsceb.jpl.nasa.gov>

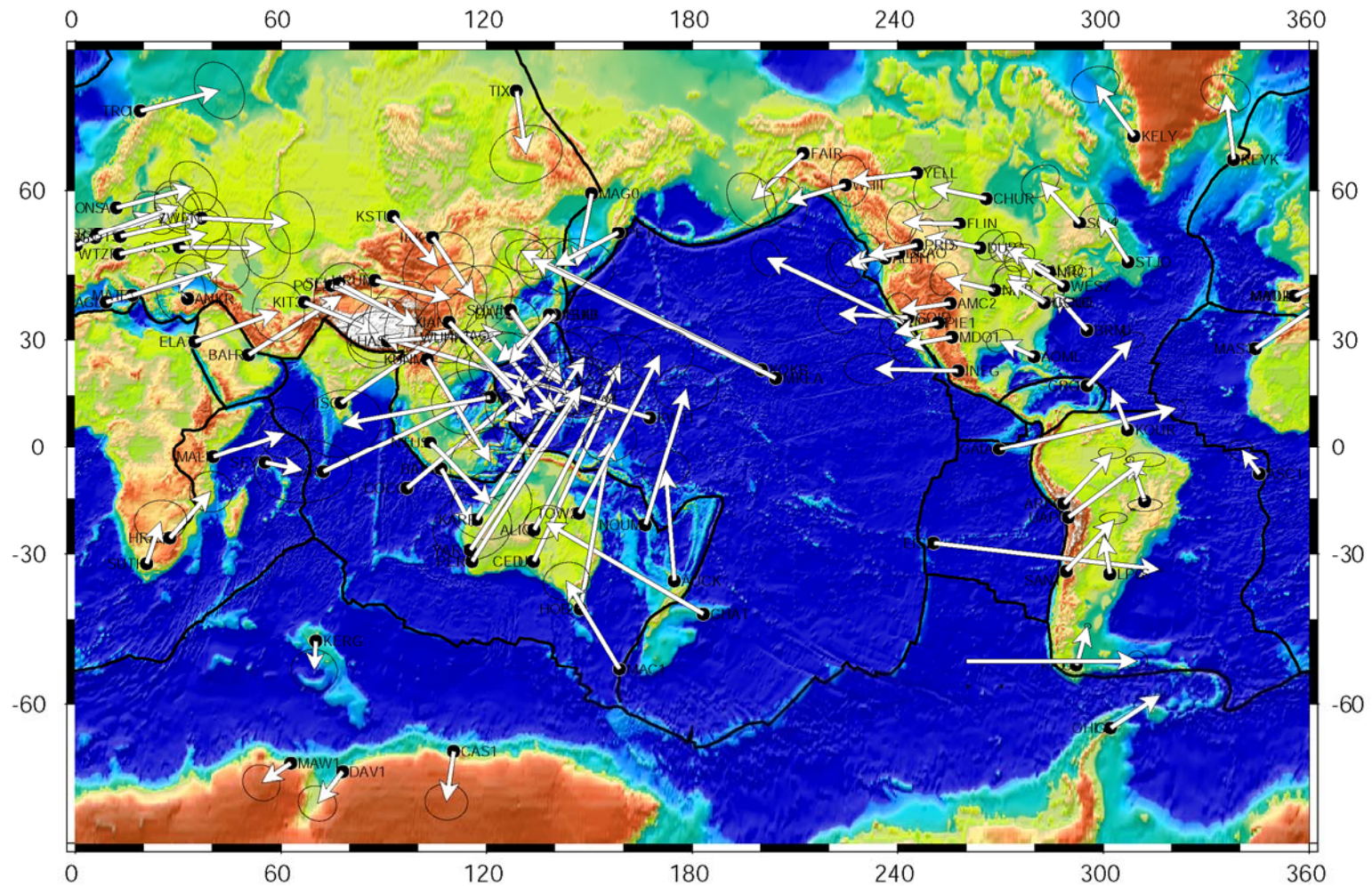


GMT May 10 17:22:02 2004

GPS Solutions : Revel, Sella et al. 2002 (ITRF97)

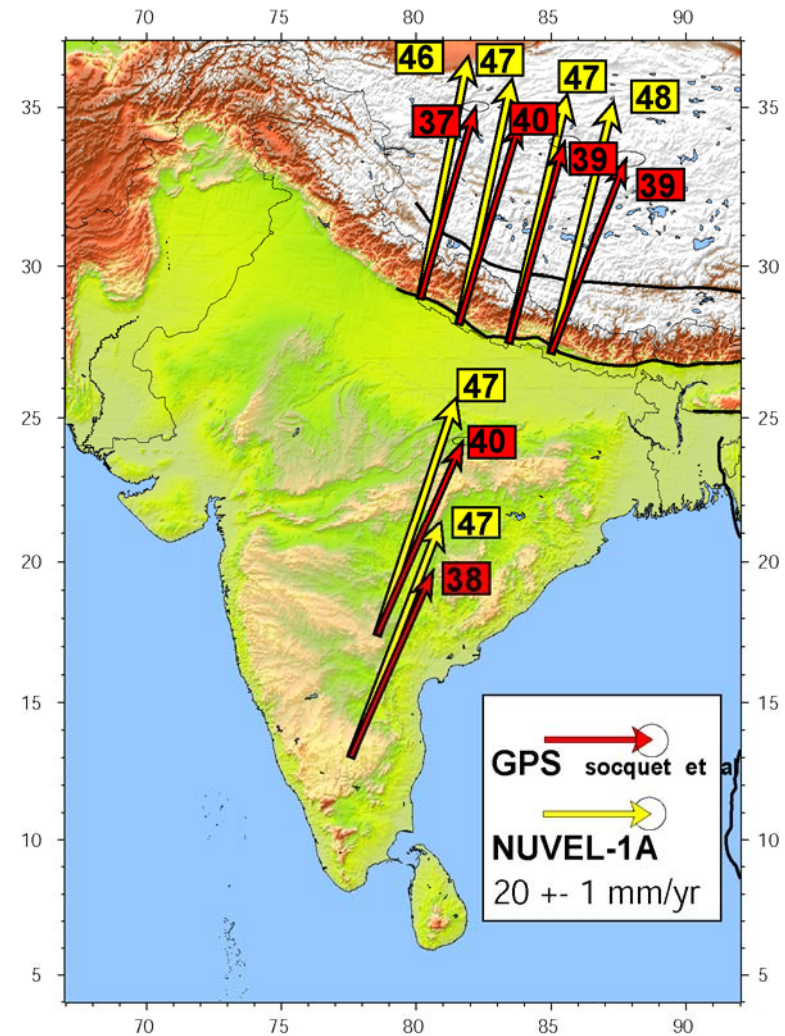
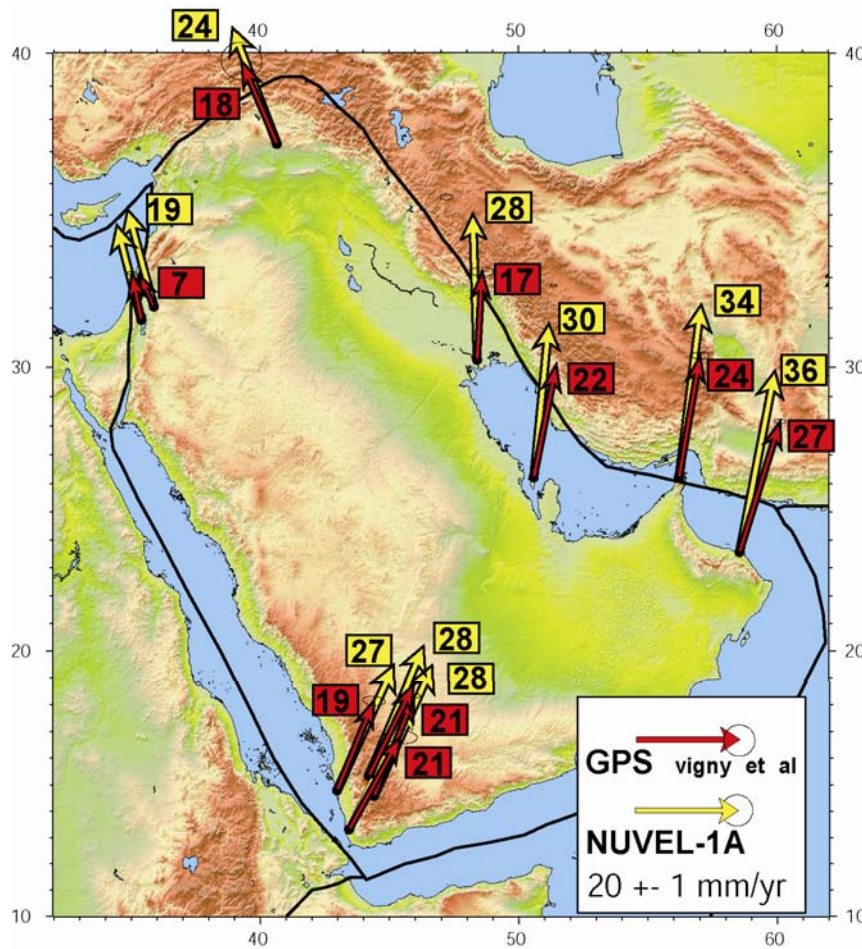


GPS Solutions : ITRF2000, Altamimi et al., 2003

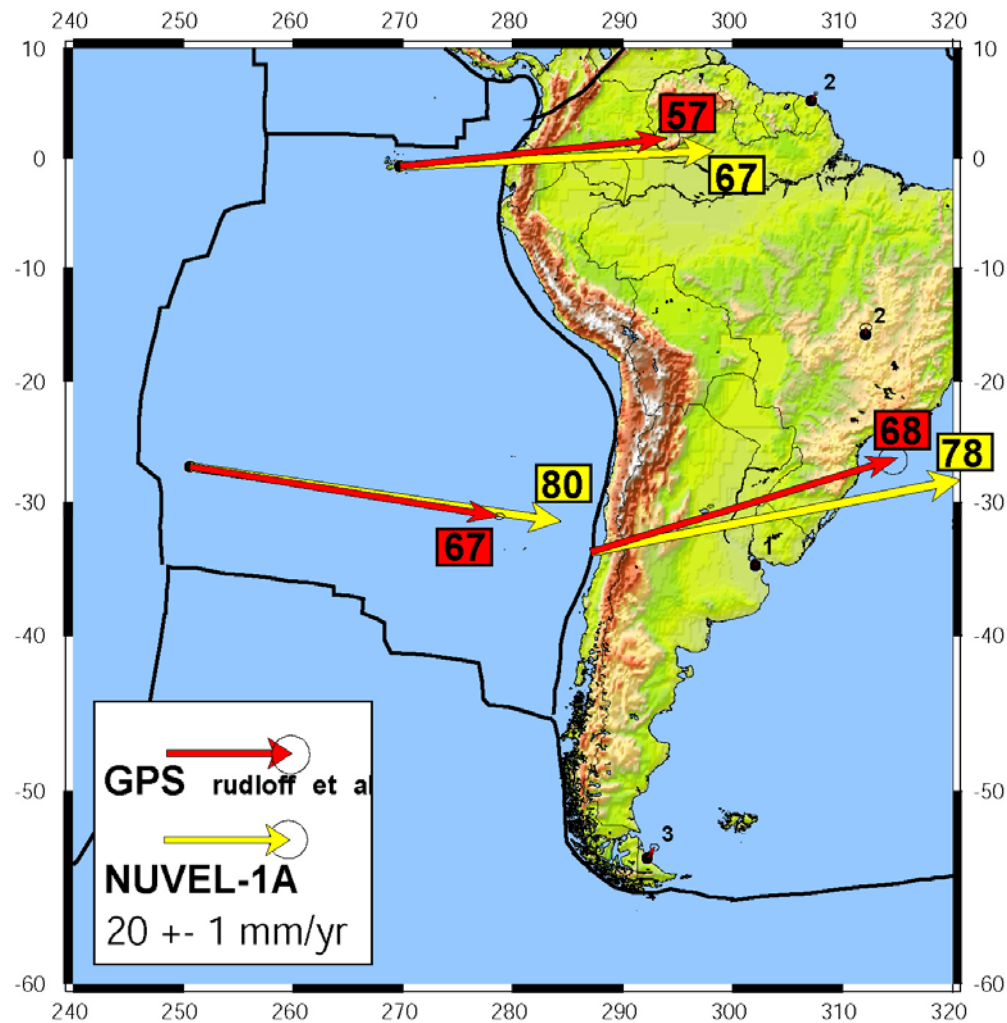


GS of CAS – Geodesy & Geodynamics – Beijing June 2004

GPS finds Arabia, India and Nazca are slower



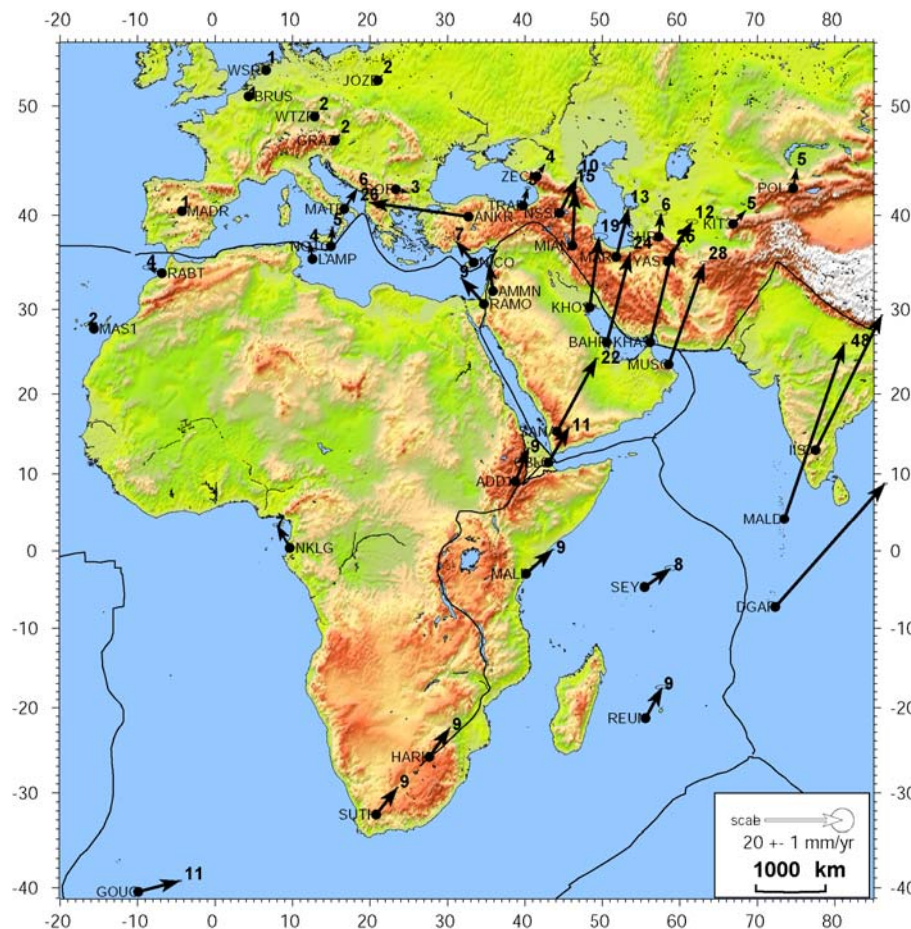
GPS finds Arabia, India and Nazca are slower



Africa Arabia India solution

Afar 91 - 03 - sol26 (ITRF 2000)

relative to NNR-Nuvel-1A Eurasia (50.6,-112.4,0.23)

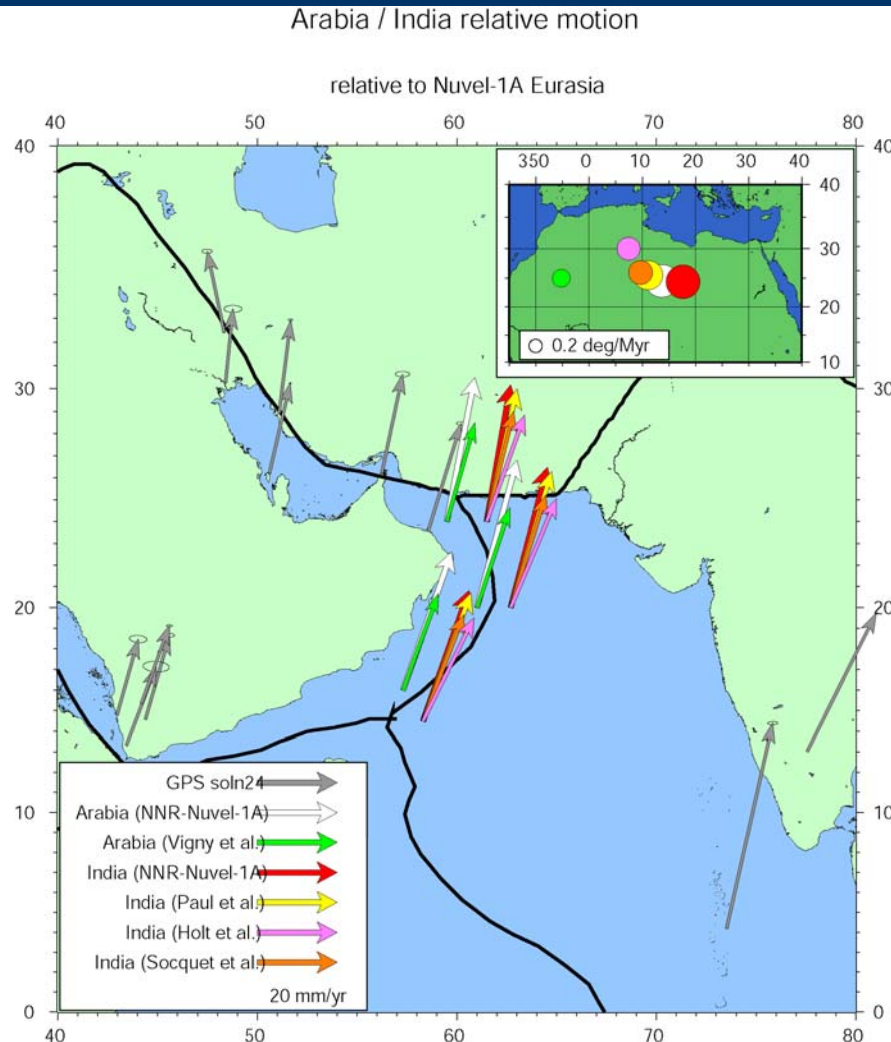


GPS velocities show :

- Africa moving slowly north against Eurasia
- Somalia being separated from Africa
- Arabia moving rapidly North against Eurasia
- India moving even faster north against Eurasia...

...but this does not mean the relative motion of India/Arabia is important

Arabia/India relative motion



The rotation poles of India and Arabia are very close to each other. So the velocity of India is higher than the velocity of Arabia **only because India is further away from the rotation pole**

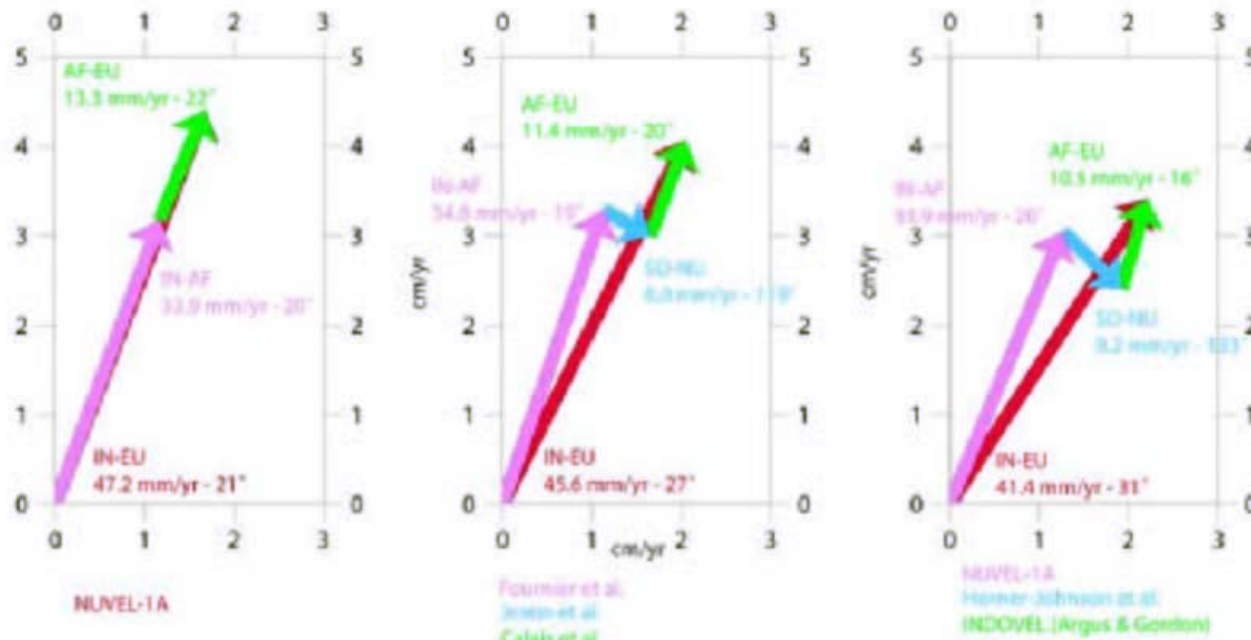
Geological velocities (white & red arrows) on the boundary between Arabia and India are almost identical

GPS determined poles allow to **predict** velocities on this boundary. They should match this condition required by Geology : there is almost no deformation there

India-Africa-Somalia-Eurasia velocity composition

Can we predict the Somalia/Africa motion based on known vectors ?

India/Eurasia velocity at Bangalore (India)

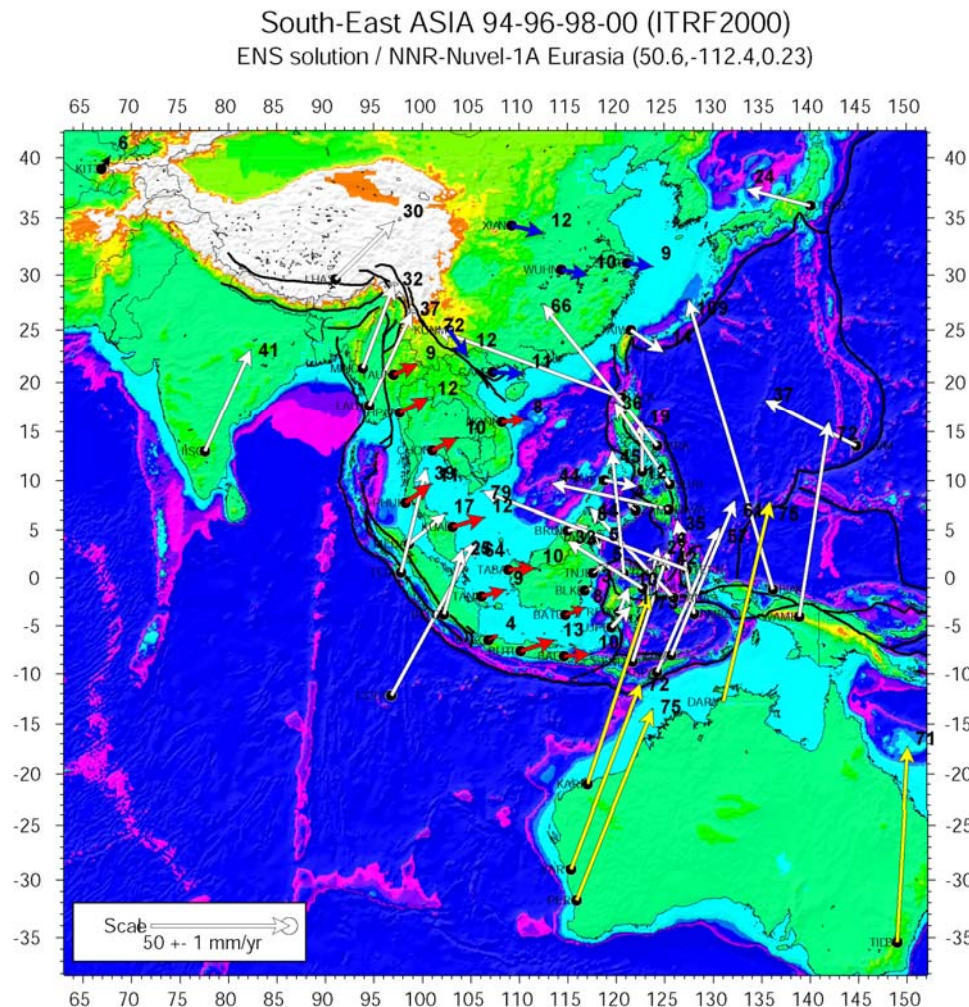


for Nuvel-1A, India/Eurasia is equal to India/Africa + Africa/Eurasia

But India/Eurasia is equal to India/Africa + **Africa/Somalia** + Somalia/Eurasia

Revised Nuvel give high (too high) velocity for Somalia

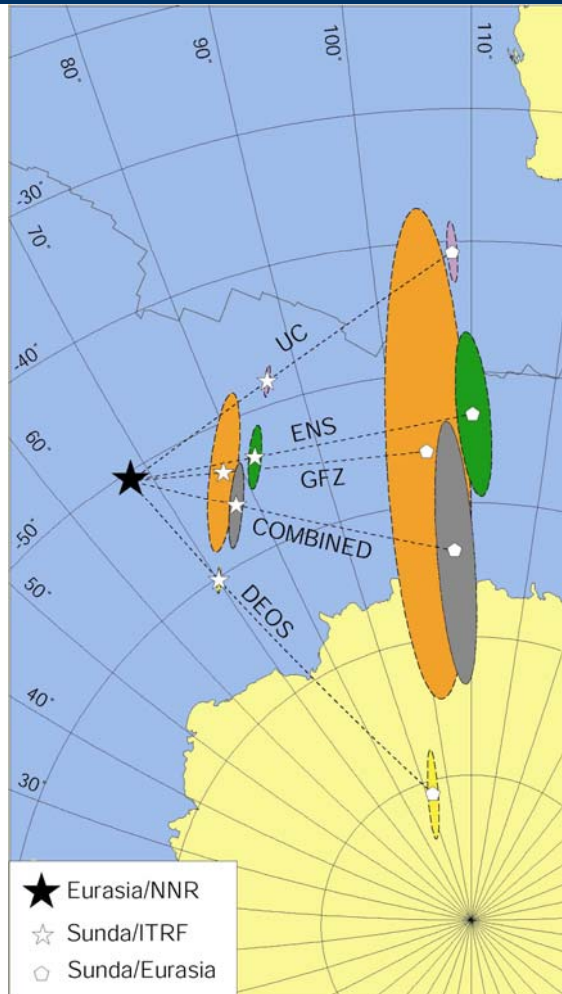
Rigid Sundaland



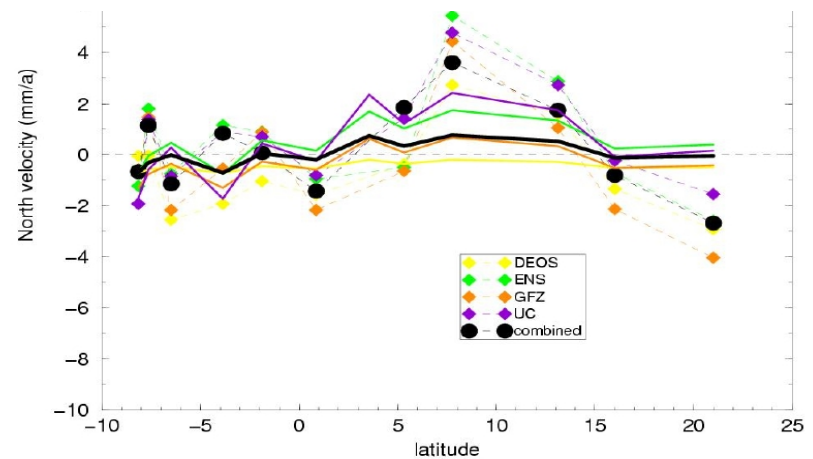
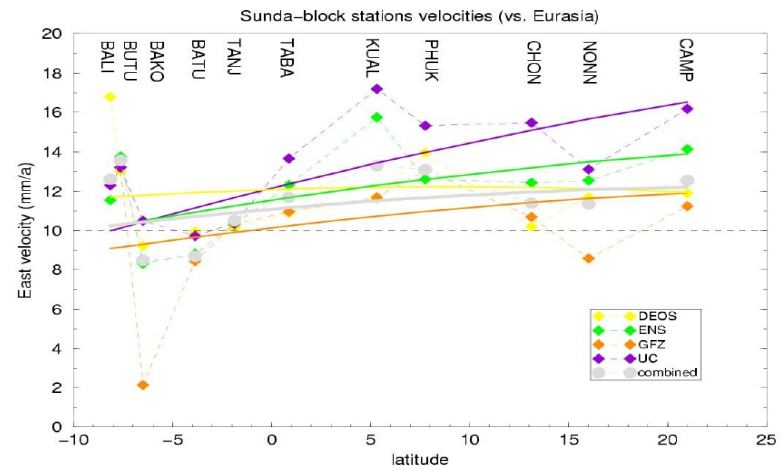
GPS campaigns with more than 60 sites allow to determine that :

- South-East Asia (red arrows) is an individual block which moves away from Eurasia (black arrows)
- South China (blue arrows) also moves away from Eurasia at around 10 mm/yr eastward

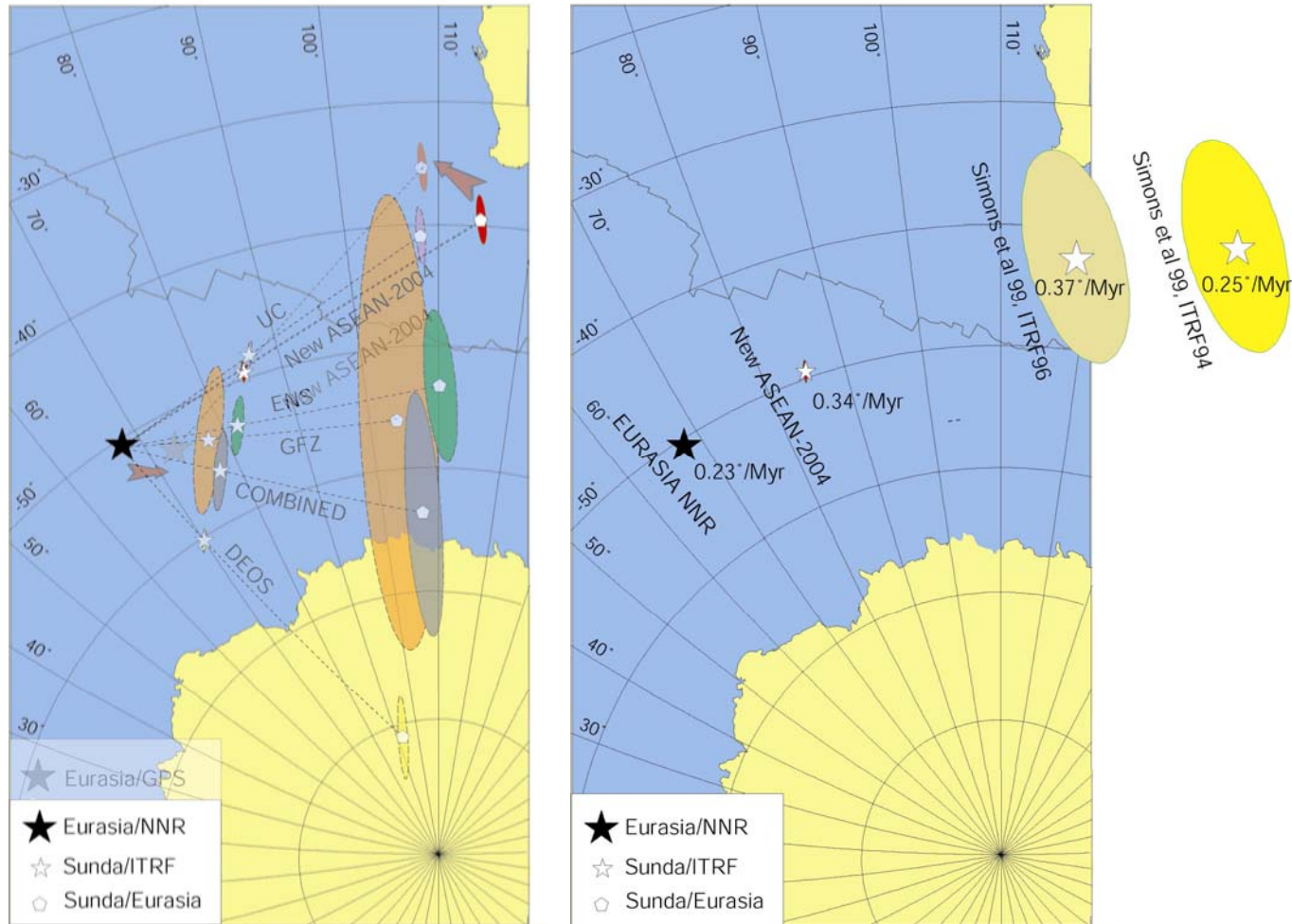
GEODYSSEA poles



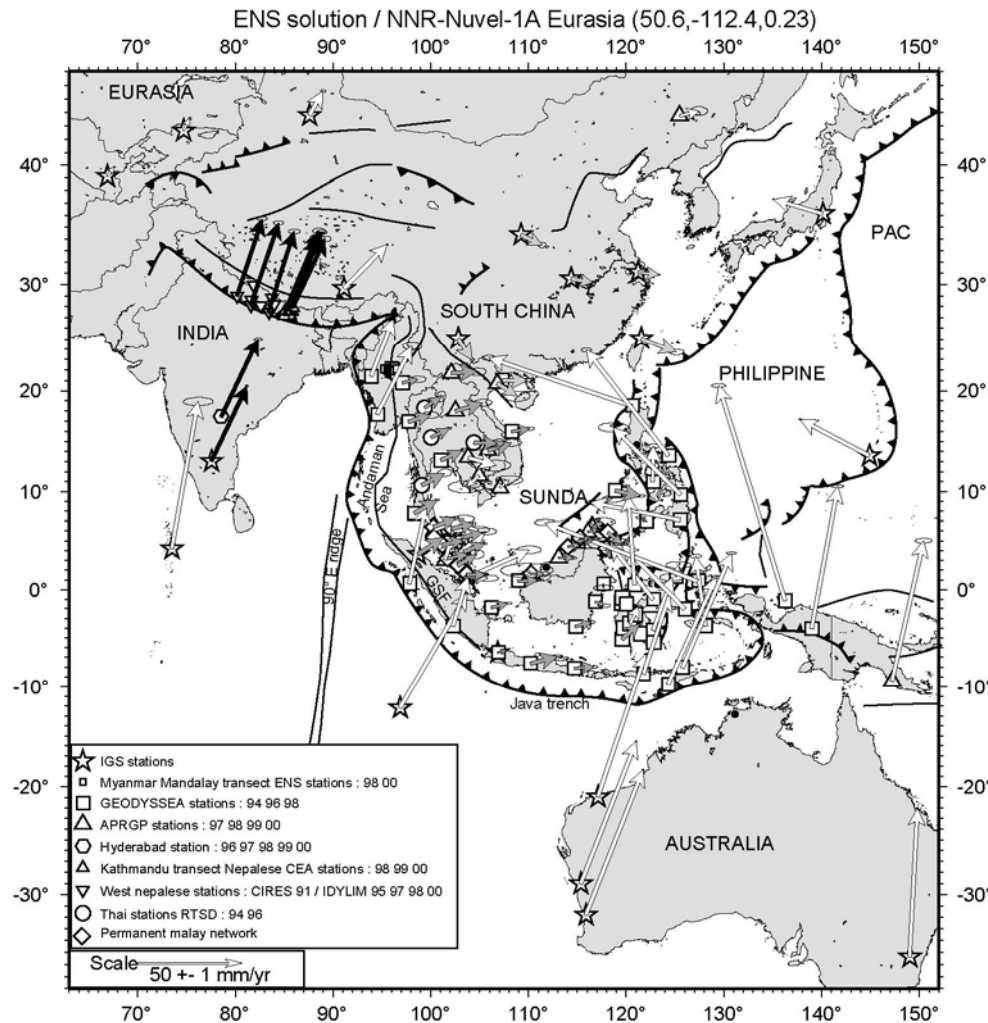
GEODYSSEA 94-96-98 – solutions comparisons



Older GEODYSSSEA poles



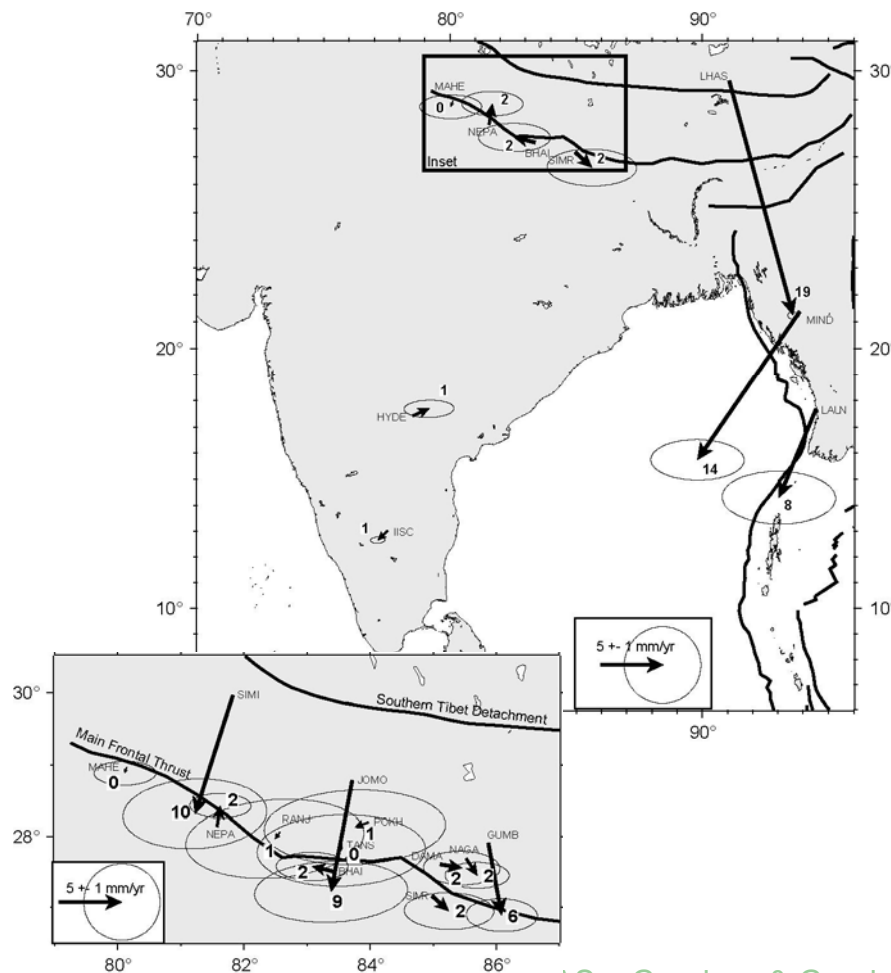
New ASEAN solution



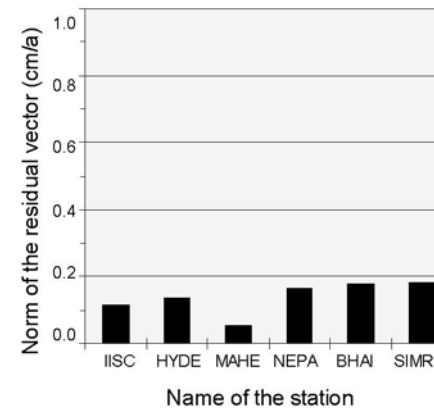
We determine the present-day relative motion between India and Sundaland as well as the horizontal crustal motion within these two plates based on a regional GPS data set including ~190 stations in Asia spanning 11 years. This data set includes GEODYSSSEA, APRGP, THAICA, permanent Malaysian network, Nepalese and Indian stations.

Indian residual velocities

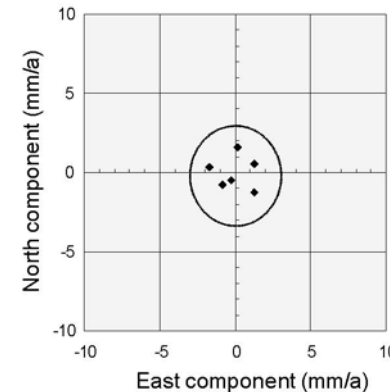
Pole positions **don't** matter ... Only **residual velocities** do



BEST FIT RESIDUALS



RESIDUAL VECTOR COMPONENTS



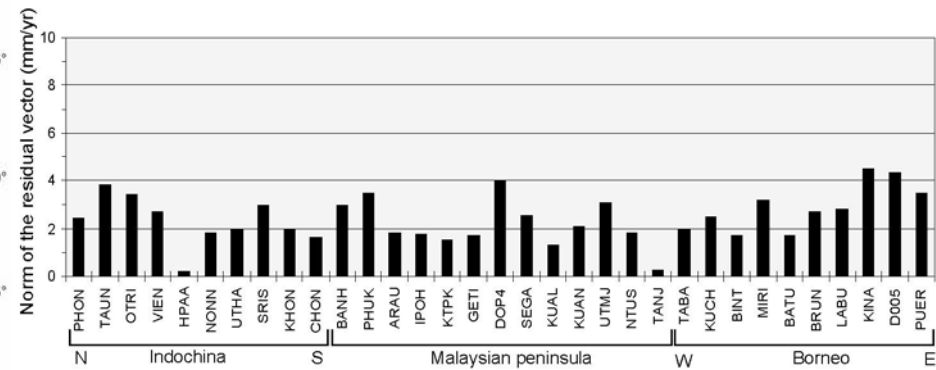
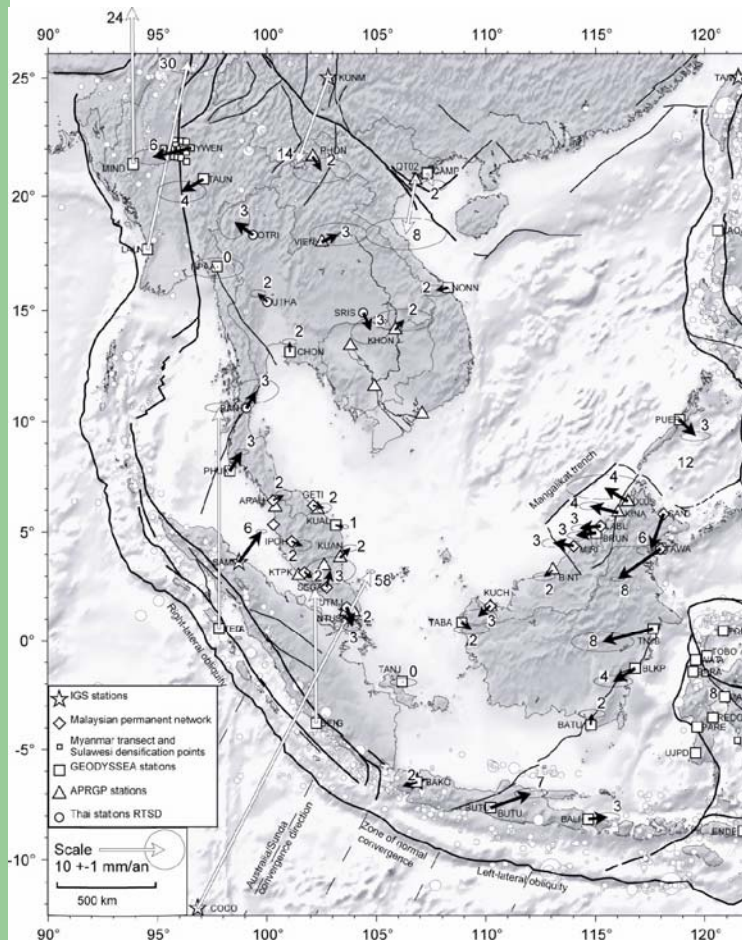
India is a very rigid plate

Residual velocities reach the bottom precision of GPS measurements

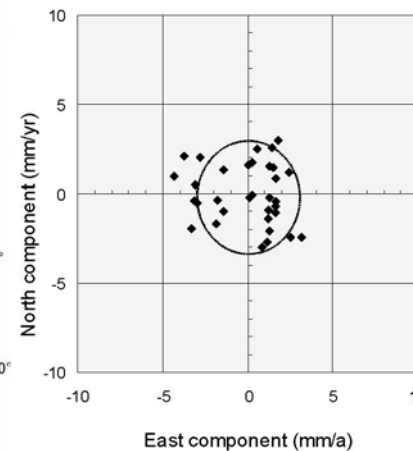
ASEAN Residual velocities

Sundaland is more deformed, at least near its boundaries

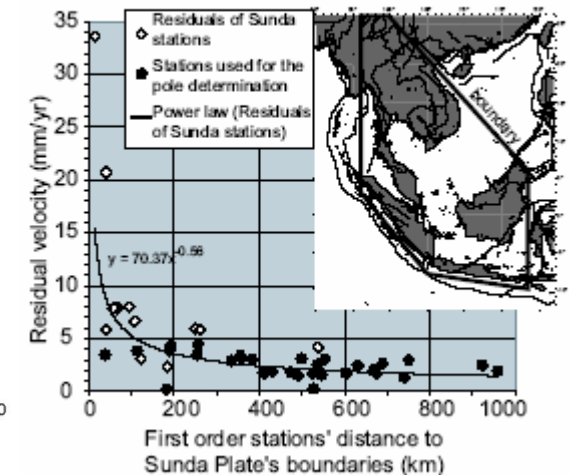
BEST FIT RESIDUALS



RESIDUAL VECTOR COMPONENTS

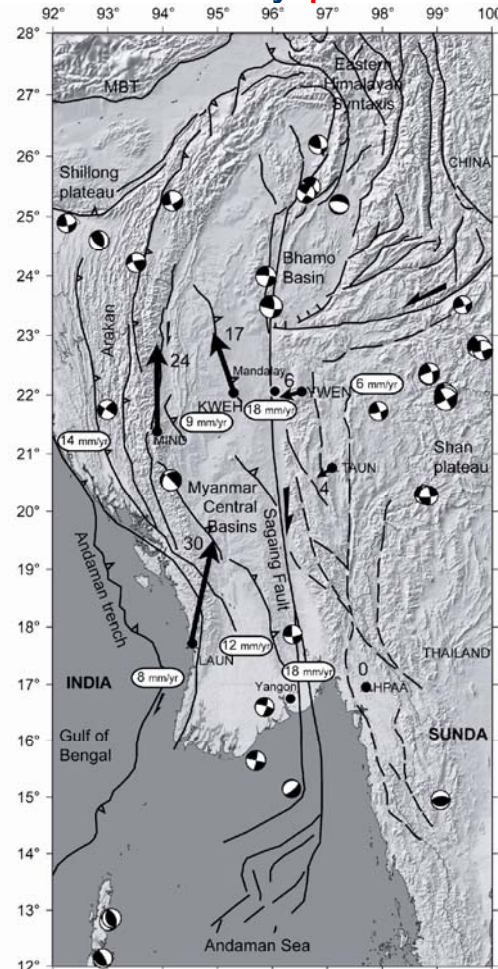
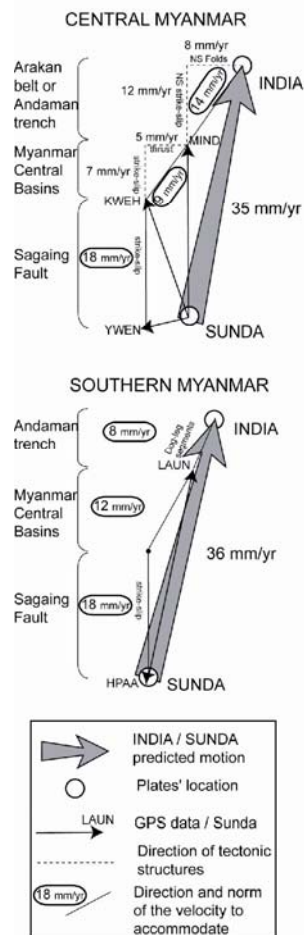


Residual velocities for Sunda stations with respect to their distance to the plate's boundaries



India/Sunda relative motion

Pole positions **don't matter**...only **predicted motions on plate boundary** do



Using the measurements we can compute the rotation pole between India and Sundaland

Using the relative pole, we can predict velocities where we don't have measurements

Then we can try to guess what is the motion on geological structures we know but we did not measure

Strain rate and rotation rate tensors (1)

To assess plate deformation :

1. Look at station velocity residuals
2. Compute strain rate and rotation rate tensors

$$\text{Strain} = \frac{\text{Velocity}}{\text{Distance}} = \frac{\text{mm/yr}}{\text{km}} = \% / \text{yr}$$

$$\text{Matrix tensor notation : } S_i^j = d(V_i) / d(x_j) = \begin{vmatrix} d(V_x) / d(x) & d(V_x) / d(y) \\ d(V_y) / d(x) & d(V_y) / d(y) \end{vmatrix}$$

$$\text{Theory says : } [S] = [E] + [W]$$

Symetrical Antisymetrical
Strain rate rotation rate

Strain rate and rotation rate tensors (2)

$$[E] = \frac{1}{2} ([S] + [S]^T) = \begin{bmatrix} E_{11} & E_{12} \\ E_{12} & E_{22} \end{bmatrix} \quad [W] = \frac{1}{2} ([S] - [S]^T) = \begin{bmatrix} 0 & W \\ -W & 0 \end{bmatrix}$$

[E] has 2 Eigen values : $\varepsilon_1, \varepsilon_2$

ε_1 and ε_2 are extension/compression along principal direction defined by angle θ (defined as angle between ε_2 direction and north)

$$\varepsilon_1 = E_{11} \cos^2\theta + E_{22} \sin^2\theta - 2 E_{12} \sin\theta \cos\theta$$

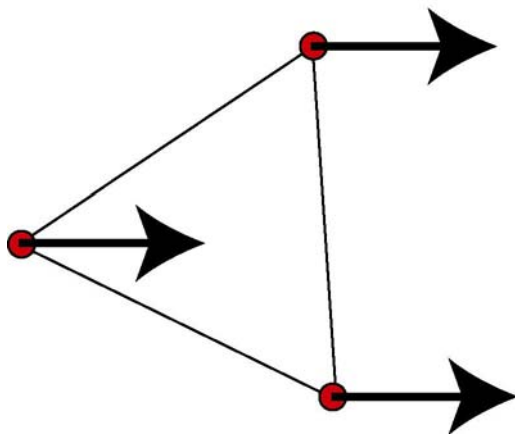
$$\varepsilon_2 = E_{11} \sin^2\theta + E_{22} \cos^2\theta - 2 E_{12} \sin\theta \cos\theta$$

Strain rate and rotation rate tensors (3)

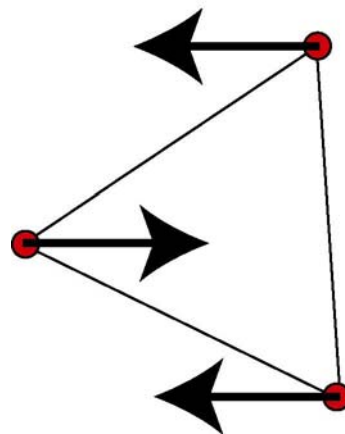
Minimum requirement to compute strain and rotation rates is :

3 velocities (to allow to determine **3 values** ϵ_1 , ϵ_2 , and W)

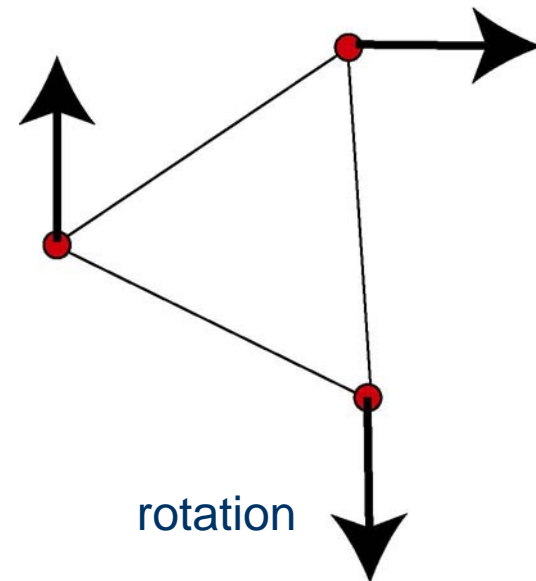
Therefore we can compute strain rate and rotation rate within any polygon, the minimum polygon being a **triangle**



No deformation



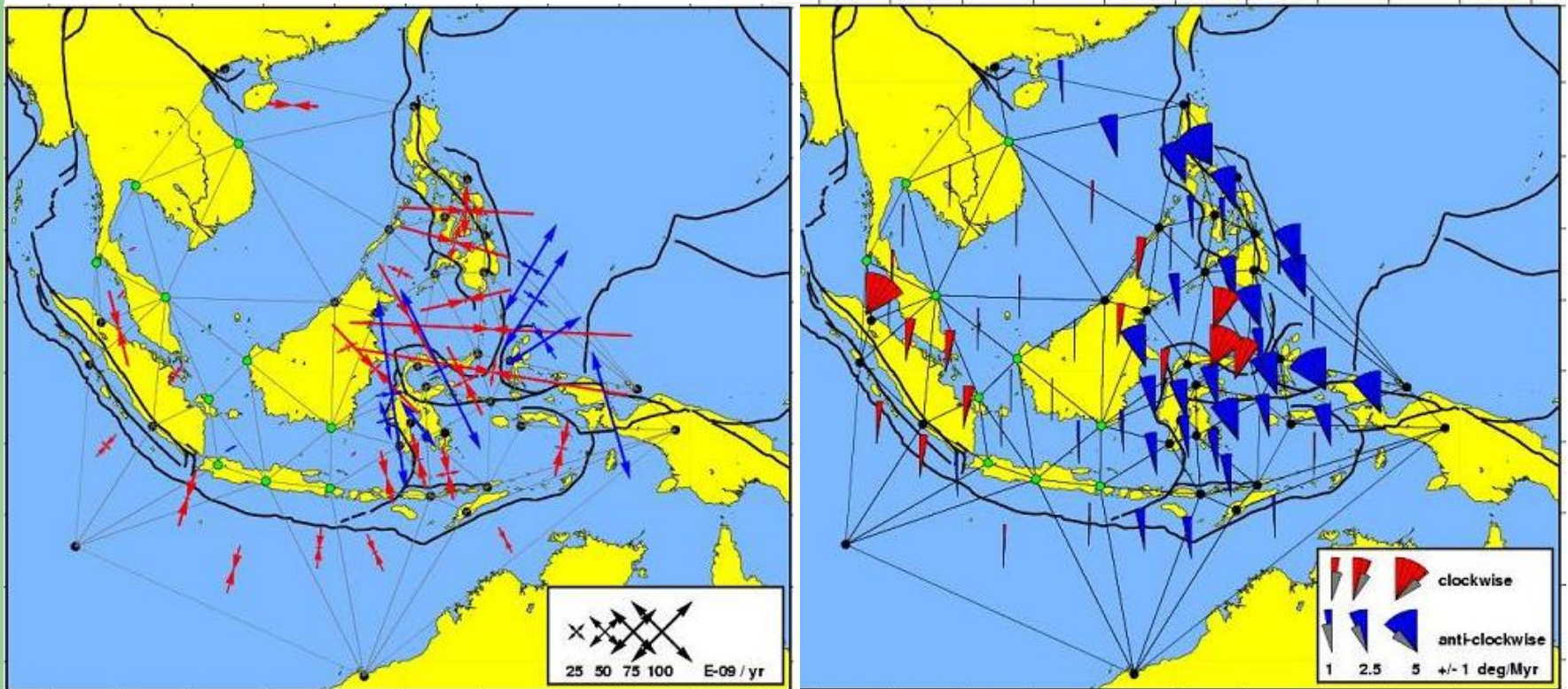
compression



rotation

Strain and rotations are **unsensitive** to reference frame

Strain and rotation in GEODYSSSEA network



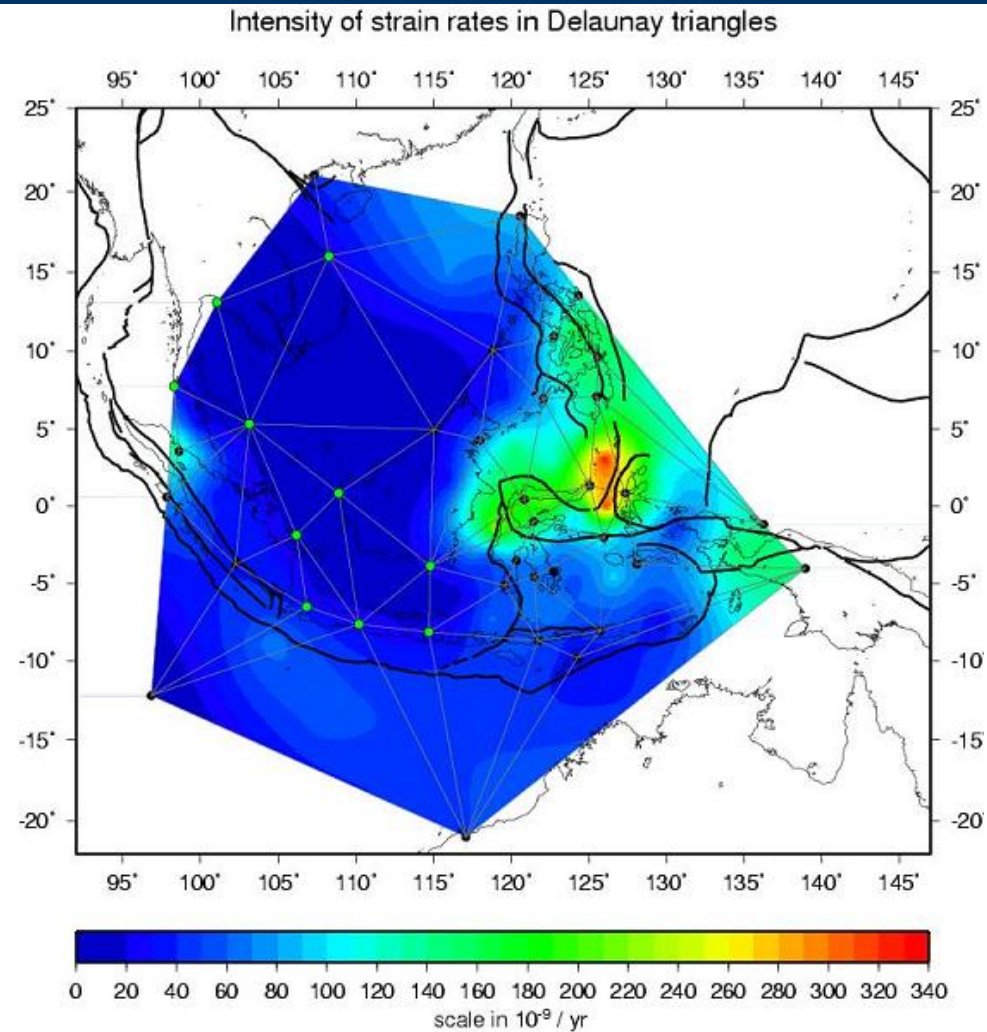
Strains :

extension/**compression**/**strike-slip**

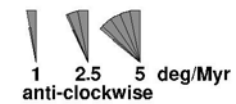
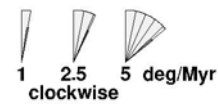
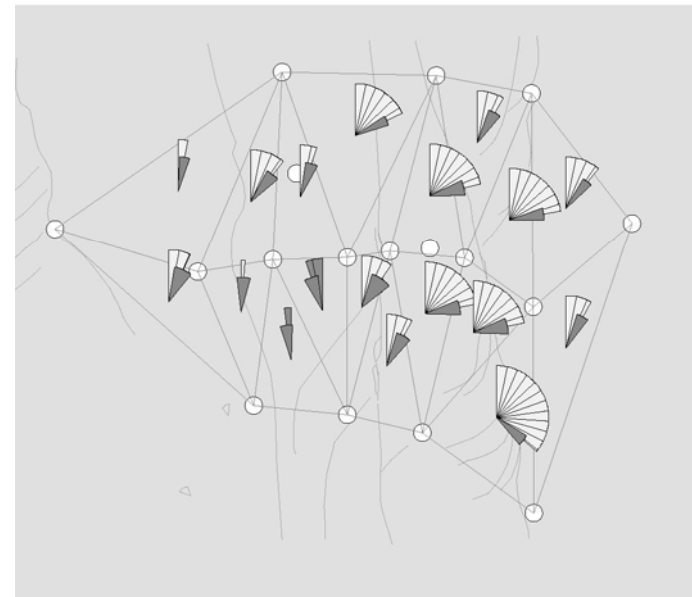
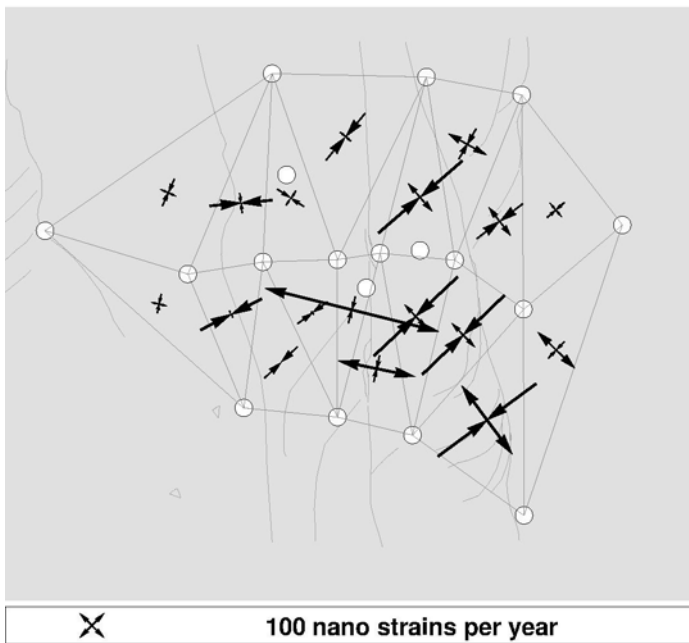
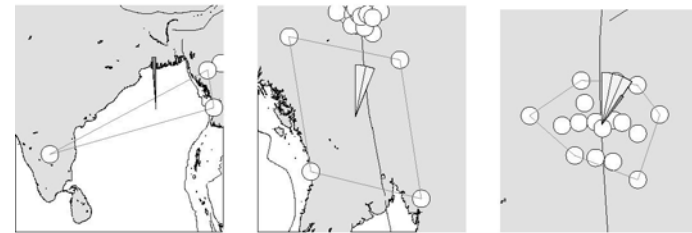
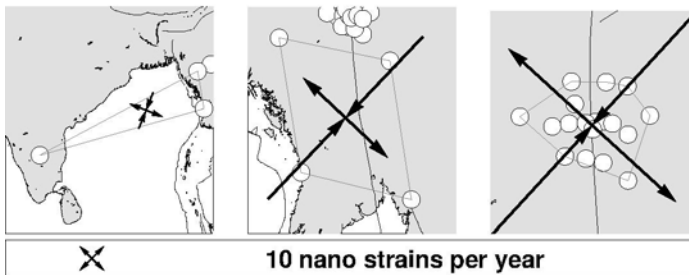
Rotations :

Anti-clockwise/**clockwise**

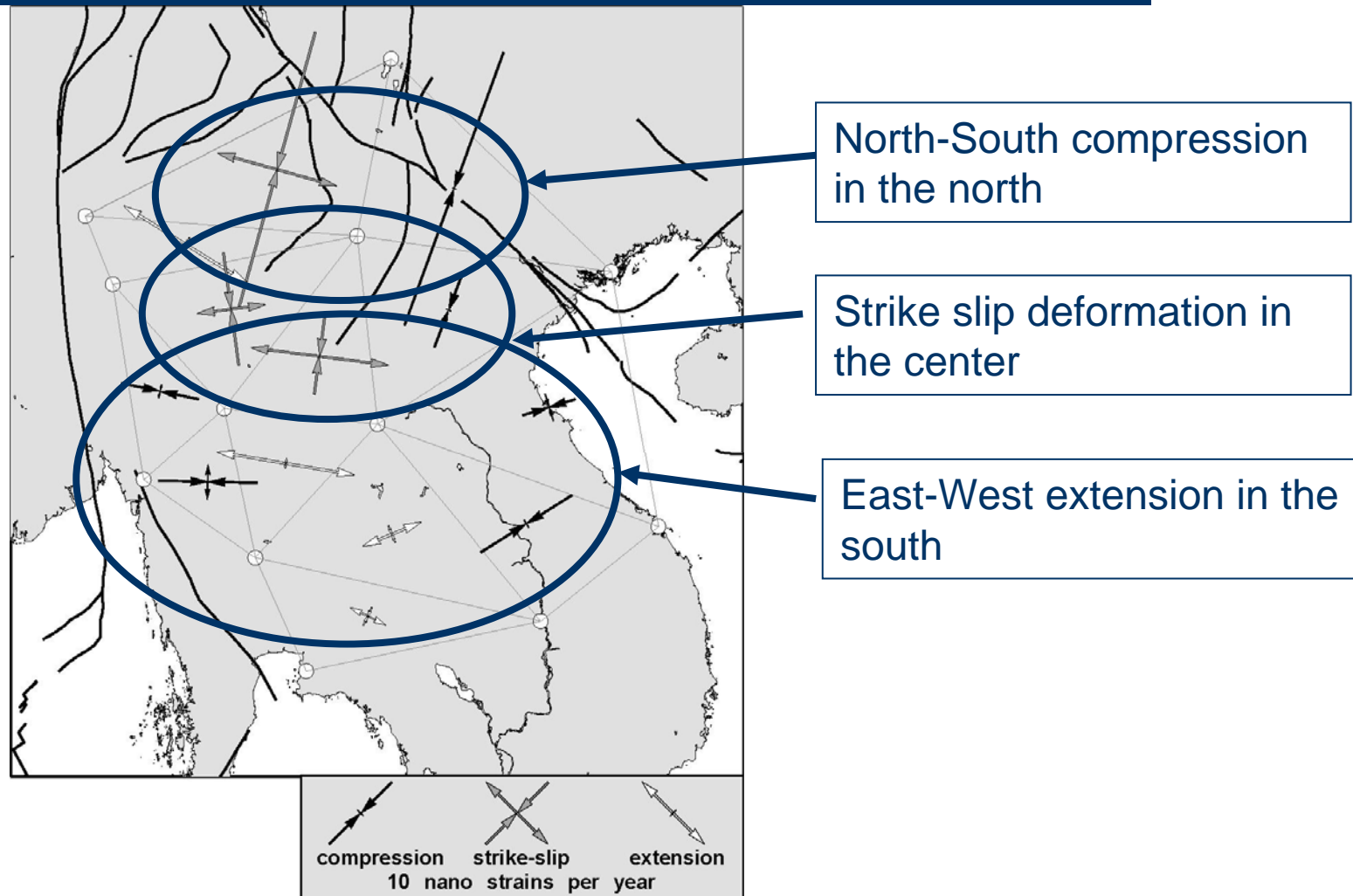
Intensity of strain in GEODYSSEA network



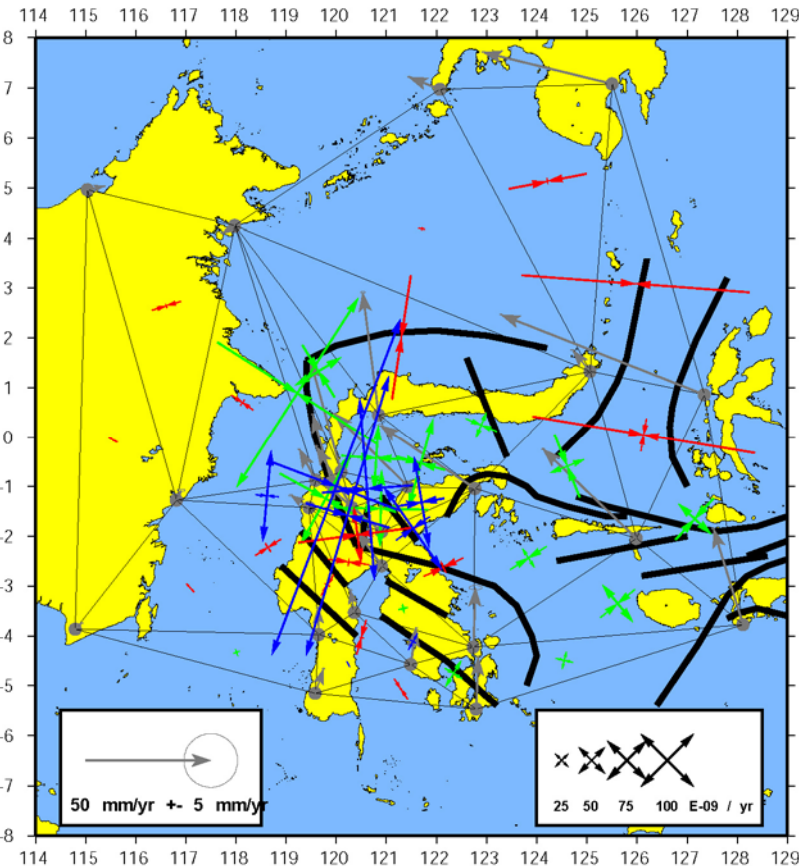
Strain and rotation in Myanmar



Strain in Northern Sundaland (Thailand)

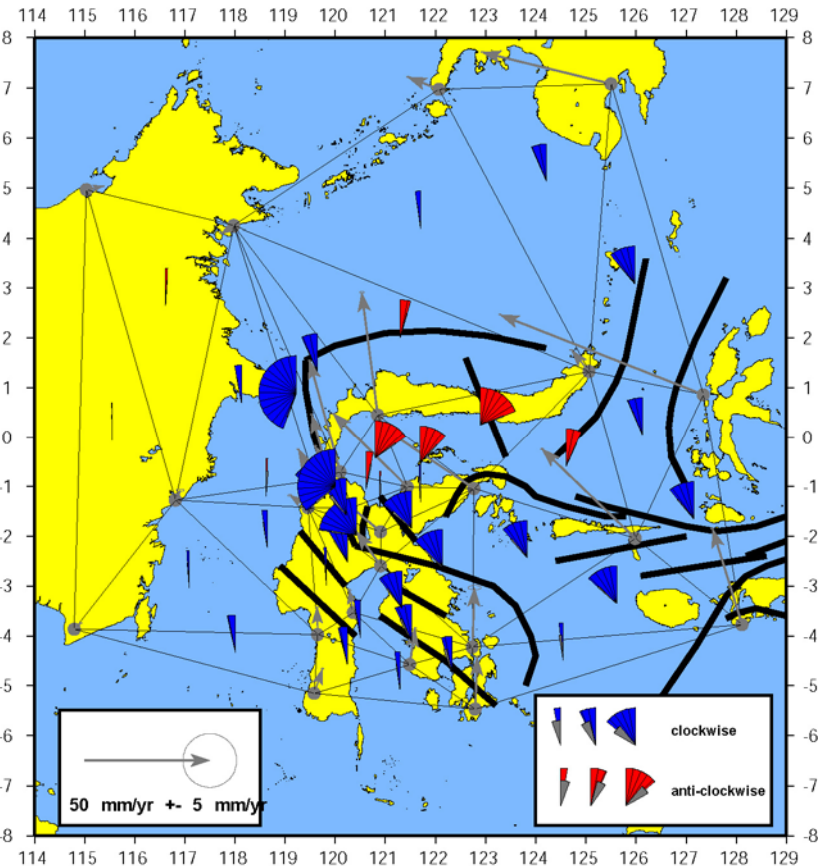


Strain and rotation in Sulawesi network



Strains :

extension/compression/strike-slip



Rotations :

Anti-clockwise/clockwise

