SEAMERGES INTRODUCTION LESSON

- Basics of GPS uncertainties/precision/errors
- Introduction to Plate tectonics
- Measuring plate tectonics/deformation with GPS
- Localized deformation on faults
- Co-seismic deformation

Basics of GPS uncertainties/precision/errors

- 1. what kind of noise/errors/uncertainties/unmodelled things affect the GPS precision : AS, SA, orbits, clocks, ionosphere, troposphere, antenna phase centers, centering (tribrachs), etc...
- 2. how do we evaluate GPS uncertainties ? (difference between formal and a posteriori) can we trust them ?
- 3. difference between precision and accuracy (internal consistency like repeatability is assertion of precision, comparison with other method affected by different biases is accuracy)
- 4. reference frames : how do we map ? with what precision ? What influence on results ?
- 5. difference between campaigns and permanent stations
- 6. spectral analysis of time series (noise/cyclic variations)

Introduction to plate tectonics

- 1. Lithospheric rigid plate definition (seismicity)
- 2. Rigid plate motions on a spherical earth : Euler pole.
- 3. Geological data and model for present day plate motion

Measuring plate tectonics/deformation with GPS

- 1. Measurement of plate tectonics with space geodesy
- 2. Rigid plate rotations
- 3. Plate deformation: strain and rotation tensors

localized deformation on faults

- 1. variation in space: arctangent elastic accumulation (theory and observations)
- 2. variation in time: seismic cycle , stick-slip, creep, silent slip, viscous relaxation

co-seismic deformation

- 1. observations and modelling
- 2. quantifying slip on faults planes
- 3. interractions of earthquakes and Coulomb stress transfer